

## Parallel-Batch Scheduling with Deterioration and Rejection on a Single Machine

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### Abstract

In this paper, we consider the bounded parallel-batch scheduling with deterioration and rejection on a single machine. A job is either rejected with a certain penalty having to be paid, or accepted and processed in batches on the single machine. The objective is to minimize the maximum completion time of the accepted jobs and the total penalty of the rejected jobs. We analyze the complexity of the problem, present a pseudo-polynomial time algorithm and a fully polynomial-time approximation scheme.

### Key words

Batch scheduling, deterioration, rejection, pseudo-polynomial time algorithm, fully polynomial-time approximation scheme (FPTAS)

### 1. Introduction

Consider the following problem of bounded parallel-batch scheduling with deterioration and rejection. There are  $n$  independent non-preemptive deteriorating jobs  $J = \{J_1, J_2, \dots, J_n\}$  to be processed on a single batch machine. The actual processing time of job  $J_j (j=1, 2, \dots, n)$  is  $p_j = \alpha_j t$ , where  $\alpha_j (\geq 0)$  and  $t$  denote the deteriorating rate and starting time, respectively.  $J_j (j=1, 2, \dots, n)$  has a rejection penalty  $e_j$  and a release date  $r_j$ . Without loss of generality, we assume that the jobs' parameters are integral, unless stated otherwise. Each job  $J_j (j=1, 2, \dots, n)$  is either rejected with a rejection penalty  $e_j$  having to be paid, or accepted to be processed on the machine in batches. The

machine can process up to  $b$  jobs simultaneously as a batch, and the processing time of the batch is equal to the longest time of any job in the batch. In the batch scheduling with deterioration, the deteriorating rate of a given batch  $B$  is defined as  $\alpha(B)=\max\{\alpha_j: J_j\in B\}$ . All jobs contained in the same batch start and complete at the same time. Once processing of a batch is initiated, it can not be interrupted and other jobs cannot be introduced into the batch until processing is completed. The objective is to minimize the maximum completion time of the accepted jobs and the total penalty of the rejected jobs. Following Gawiejnowicz (2008), we denote our problem as:

$$1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$$

where "p-batch" means parallel-batch, "rej" and "S" denote rejection and the set of accepted jobs, respectively.

The model described above falls into three categories: parallel-batch scheduling, scheduling with deterioration and scheduling with rejection. The parallel-batch scheduling is motivated by burn-in operations in semiconductor manufacturing, see Lee et al. (1992) for more details of the background. By Brucker et al. (1998), there are two distinct models: the bounded model, in which the bound  $b$  for each batch size is effective, i.e.,  $b < n$ , and the unbounded model, in which there is effectively no limit on the size of batch, i.e.,  $b \geq n$ . The extensive survey of different models and results were provided both by Potts and Kovalyov (2000). Afterwards, Yuan et al. (2009) gave some new results for this parallel-batch scheduling.

Scheduling with deteriorating job was first considered by Gupta and Gupta (1988), and Browne and Yechiali (1990). From then on, this scheduling model has been extensively studied. The monograph by Gawiejnowicz (2008) presents this scheduling from different perspectives and covers results and examples. Ji and Cheng (2009) and Liu et al. (2012) gave some new results for this scheduling.

In classical scheduling literatures, all jobs must be processed. In the practical applications, however, this may not be true. Due to the limited resources, the scheduler can have the option to reject some jobs. However, rejected jobs will incur rejection penalties. The scheduling with rejection was first considered by Bartal et al. (2000). They studied both the off-line and the on-line versions of scheduling with rejection on identical parallel machines, the objective is to minimize the maximum completion time of the accepted jobs and the total penalty of the rejected jobs. Subsequently, the scheduling with rejection has many results.

Cheng and Sun (2009) considered the scheduling with linear deteriorating jobs and rejection on a single machine, they gave the proofs of the NP-hardness and presented some pseudo-

polynomial time algorithms and FPTASs for some objectives. Li and Yuan (2009) gave some results for the deteriorating job scheduling with rejection on parallel machines.

In this paper, we consider the bounded parallel-batch scheduling with deterioration and rejection on a single machine. The objective is to minimize the maximum completion time of the accepted jobs and the total penalty of the rejected jobs.

The rest of the paper is organized as follows. We present some preliminaries in Section 2. In Section 3, we analyze complexity of the problem, present a pseudo-polynomial time algorithm, and a fully polynomial-time approximation scheme for the case where the jobs have identical release dates is presented. We conclude the paper and suggest some new topics for future research in the last section.

## 2. Preliminaries

An algorithm is called a  $(1+\varepsilon)$ -approximation algorithm for a minimization problem if it produces a solution that is at most  $1+\varepsilon$  times as big as the optimal value, running in time that is polynomial in the input size. A family of algorithms  $\{A_\varepsilon\}$  for a problem is called a polynomial time approximation scheme (PTAS, for short) if, for every  $\varepsilon > 0$   $\{A_\varepsilon\}$  is a  $(1+\varepsilon)$ -approximation algorithm whose running time is polynomial in the input size. Furthermore, if the running time of every  $\{A_\varepsilon\}$  is bounded by a polynomial in the input size and  $1/\varepsilon$ , then the family is called a fully polynomial time approximation scheme (FPTAS for short). Algorithms that have running times polynomial in  $n$  and the maximum of the elements of the instance are called pseudo-polynomial time algorithms.

We list the following useful algorithm stated in Miao et al. (2011).

**Algorithm FBLDR** (Fully Batching Longest Deteriorating Rate)

**Step 1:** Re-index jobs in non-increasing order of their deteriorating rates such that.  $\alpha_1 \geq \alpha_2 \geq \dots \geq \alpha_n$ .

**Step 2:** Form batches by placing jobs  $J_{jb+1}$

through  $J_{(j+1)b}$  together in the same batch, for  $j = 1, 2, \dots, \left\lfloor \frac{n}{b} \right\rfloor$ .

**Step 3:** Schedule the batches in any arbitrary order.

The schedule contains at most  $\left\lfloor \frac{n}{b} \right\rfloor + 1$  batches and all batches are full except possibly the last one, where  $\left\lfloor \frac{n}{b} \right\rfloor$  denotes the largest integer less than  $\frac{n}{b}$ .

**Lemma 1.** (Cheng et al. 2009) Problem  $1|p_j = \alpha_j t, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$  is NP-hard.

**Lemma 2.** (Woeginger 1999) For any  $0 \leq y \leq 1$  and for any real  $m \geq 1$ ,  $(1 + \frac{y}{m})^m \leq 1 + 2y$  holds.

**Lemma 3.** (Mosheiov 1994) For the single machine scheduling problem  $1|p_j = \alpha_j t|C_{\max}$ , if a schedule  $\pi = \{J_{[1]}, J_{[2]}, \dots, J_{[n]}\}$ , the starting time of job  $J_{[1]}$  is  $t_0$ , then the makespan is  $C_{\max} = t_0 \prod_{j=1}^n (1 + \alpha_{[j]})$ .

The geometric rounding technique developed by Sengupta (2003) is stated as: For any  $\varepsilon' > 0$ , and  $x \geq 1$ , if  $(1 + \varepsilon')^{k-1} < x < (1 + \varepsilon')^k$ , then we define  $\lfloor x \rfloor_{\varepsilon'} = (1 + \varepsilon')^{k-1}$ ,  $\lceil x \rceil_{\varepsilon'} = (1 + \varepsilon')^k$ . If  $x$  is an exact power of  $1 + \varepsilon'$ , then  $\lfloor x \rfloor_{\varepsilon'} = \lceil x \rceil_{\varepsilon'} = x$ . Note that  $\lceil x \rceil_{\varepsilon'} \leq (1 + \varepsilon')^k x$  for any  $x \geq 1$ .

### 3. Mainresults

#### 3.1 NP-hardness

From Lemma 1 and Zhang and Miao (2004), we can get the following theorem.

**Theorem 1.** Problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$  is NP-hard.

#### 3.2 Pseudo-polynomial time algorithm

**Theorem 2.** For problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$ , there exists an optimal schedule in which the accepted jobs are assigned to the machine by Algorithm FBLDR.

Assume that the jobs have been indexed so that  $\alpha_1 \geq \alpha_2 \geq \dots \geq \alpha_n$

Let  $F_j(b_j, E)$  be the optimal value of the objective function satisfying the following conditions for problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in S} e_j$ :

(i) The jobs in consideration are  $\{J_1, \dots, J_j\}$ .

(ii) The number of processed jobs in the last batch is  $b_j$ . If there is no such batch, we set  $b_j = 0$ .

(iii) The total rejection penalty of rejected jobs is  $E$ .

To get  $F_j(b_j, E)$ , we distinguish two cases as follows.

*Case 1. Job  $J_j$  is accepted*

In this case, we distinguish two subcases.

*Subcase 1.1.  $b_j = 1$*

In this subcase, job  $J_j$  has to start a new batch. The number of processed jobs in the last batch among  $\{J_1, \dots, J_{j-1}\}$  is 0 or  $b$ . Without loss of generality, let it be  $b$ . Then the maximum completion time of accepted jobs among  $\{J_1, \dots, J_{j-1}\}$  is  $F_{j-1}(b, E) - E$ , which is the starting time of job  $J_j$ . Then we have

$$F_j(b_j, E) = (1 + \alpha_j)(F_{j-1}(b, E) - E) + E = (1 + \alpha_j)F_{j-1}(b, E) - \alpha_j E$$

*Subcase 1.2.  $b_j > 1$*

In this subcase, job  $J_j$  can be assigned to the last batch which has existed, and the makespan does not change by inserting job  $J_j$ . Therefore,

$$F_j(b_j, E) = F_{j-1}(b_j - 1, E).$$

*Case 2. Job  $J_j$  is rejected*

Since  $J_j$  is rejected, the total rejection penalty is  $E - e_j$  among  $\{J_1, \dots, J_{j-1}\}$ . Therefore, we have  $F_j(b_j, E) = F_{j-1}(b_j, E - e_j) + e_j$ .

Combining the above two cases, we design algorithm as follows.

**Algorithm DP1**

**Step 1: (Initialization)**  $F_1(1,0) = t_0(1 + \alpha_j)$  and  $F_1(b_1, E) = +\infty$  for  $(b_1, E) \neq (1,0)$ .

$F_1(0, e_1) = t_0 + e_1$  and  $F_1(b_1, E) = +\infty$  for  $(b_1, E) \neq (0, e_1)$ .

**Step 2: (Iteration)**

If  $b_j = 1$ ,  $F_j(b_j, E) = \min\{(1 + \alpha_j)F_{j-1}(b_j, E) - \alpha_j E, F_{j-1}(b_j, E - e_j) + e_j\}$

If  $b_j > 1$ ,  $F_j(b_j, E) = \min\{F_{j-1}(b_j - 1, E), F_{j-1}(b_j, E - e_j) + e_j\}$

**Step 3: (Solution)** .

Define the optimal value

$$F^* = \min \left\{ F_n(b_n, E) : 0 \leq b_n \leq b, 0 \leq E \leq \sum_{j=1}^n e_j \right\}$$

**Theorem 3.** Algorithm DP1 solves problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{j \in \bar{S}} e_j$  in

$O(nb \sum_{j=1}^n e_j)$  time.

**Proof :** The correctness of Algorithm DP1 is guaranteed by the above discussion. Clearly,

we have  $0 \leq b_i \leq b$  for  $i = 1, 2, \dots, n$  and  $0 \leq E \leq \sum_{j=1}^n e_j$ . Thus, the recursive function has at most

$O(nb \sum_{j=1}^n e_j)$  states. Each iteration takes a constant time to execute. Hence, the running time of the

Algorithm DP1 is  $O(nb \sum_{j=1}^n e_j)$ .

### 3.3 A Fully polynomial-time approximation scheme

In this subsection, motivated by Cheng and Sun (2009), we design an FPTAS for problem

$1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{j \in \bar{S}} e_j$  by considering the modified deteriorating rates of the

scheduled jobs. The definition of the modified deteriorating rates involves the rounding technique stated in Section 2.

For any  $\varepsilon > 0$ , we define the modified deteriorating rates  $\alpha_j' = \lceil 1 + \alpha_j \rceil_{\varepsilon'} - 1$ , where  $\varepsilon' = \frac{\varepsilon}{2 \lceil \frac{n}{b} \rceil}$  and  $\lceil \frac{n}{b} \rceil$  denotes the smallest integer larger than equal to  $\frac{n}{b}$ . Let  $L_j$  denote the

exponent of  $1 + \alpha_j'$ , i.e.,  $1 + \alpha_j' = (1 + \varepsilon')^{L_j}$ , then  $L_j = \frac{\log \lceil 1 + \alpha_j \rceil_{\varepsilon'}}{\log(1 + \varepsilon')} = O\left(\frac{\lceil \frac{n}{b} \rceil \log(1 + \alpha_j)}{\varepsilon}\right)$ .

We propose a dynamic programming algorithm for problem 1  $|p_j = \alpha_j t, b < n, rej| C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$  with modified deteriorating rates  $\alpha_j'$ .

Assume that the jobs have been indexed so that  $\alpha_1' \geq \alpha_2' \geq \dots \geq \alpha_n'$ . We define  $\varphi_k = (1 + \varepsilon')^k$ . Let  $F_j(b_j, k)$  be the optimal value of the objective function satisfying the following conditions.

(i) The jobs in consideration are  $\{J_1, \dots, J_j\}$ .

(ii) The number of processed jobs in the last batch is  $b_j$ . If there is no such batch, we set  $b_j = 0$ .

(iii) The maximum completion time of the accepted jobs is  $t_0 \varphi_k$ .

To get  $F_j(b_j, k)$ , we distinguish two cases as follows.

*Case 1. Job  $J_j$  is accepted*

In this case, we distinguish two subcases.

*Subcase 1.1.  $b_j = 1$*

In this subcase, job  $J_j$  has to start a new batch. The number of processed jobs in the last batch among  $\{J_1, \dots, J_{j-1}\}$  is 0 or  $b$ . Without loss of generality, let it be  $b$ . Then the maximum completion time of accepted jobs among  $\{J_1, \dots, J_{j-1}\}$  is  $t_0 \varphi_{k-L_j}$ . Thus, the objective value increased by  $t_0 \alpha_j' \varphi_{k-L_j}$ . Therefore,  $F_j(b_j, k) = F_{j-1}(b, k - L_j) + t_0 \alpha_j' \varphi_{k-L_j}$ .

*Subcase 1.2.  $b_j > 1$*

In this subcase, job  $J_j$  can be assigned to the last batch which has existed, and the makespan does not change by inserting job  $J_j$ . Thus,,

$$F_j(b_j, k) = F_{j-1}(b_j - 1, k).$$

*Case 2.* Job  $J_j$  is rejected

Similar to the above discussion, we have  $F_j(b_j, k) = F_{j-1}(b_j, k) + e_j$ .

Combining the above two cases, we design algorithm as follows.

### Algorithm DP2

**Step 1:** For any  $\varepsilon > 0$ , set  $\varepsilon' = \frac{\varepsilon}{2 \left\lceil \frac{n}{b} \right\rceil}$ . Given

an instance  $I$ , we define a new instance  $I'$  by rounding  $\alpha_j$  such that  $\alpha_j' = \lceil 1 + \alpha_j \rceil_{\varepsilon'} - 1$ .

**Step 2:** Index the jobs so that  $\alpha_1' \geq \alpha_2' \geq \dots \geq \alpha_n'$ .

**Step 3:** (Dynamic Programming)

**Step 3.1:**(Initialization)

$$F_1(1, L_1) = t_0 \varphi_{L_1} \quad \text{and} \quad F_1(b_1, k) = +\infty \text{ for } (b_1, k) \neq (1, L_1).$$

$$F_1(0, 0) = t_0 + e_1 \quad \text{and} \quad F_1(b_1, k) = +\infty \text{ for } (b_1, k) \neq (0, 0).$$

**Step 3.2:** (Iteration)

$$F_j(b_j, k) = \min\{F_{j-1}(b_j, k - L_j) + t_0 \alpha_j' \varphi_{k-L_j}, F_{j-1}(b_j, k) + e_j\}$$

for  $b_j = 1$ .

$$F_j(b_j, k) = \min\{F_{j-1}(b_j - 1, k), F_{j-1}(b_j, k) + e_j\}$$

for  $b_j > 1$ .

**Step 3:** (Solution).

Define the optimal value

$$\min \left\{ F_n(b_n, k) : 0 \leq b_n \leq b, 0 \leq k \leq \sum_{j=1}^n L_j \right\}.$$



Let  $F'^*$  and  $F^*$  be the optimal value for problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$

with modified deteriorating rates and problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$ ,

respectively.

**Theorem 4.** For any given  $0 \leq \varepsilon \leq 2$ ,  $\frac{F'^*}{F^*} \leq 1 + \varepsilon$ .

**Proof :** Let  $S$  be the set of accepted jobs and  $T$

be the set of batches scheduled by algorithm FBLDR from  $S$ . We  $|T| = \left\lceil \frac{|S|}{b} \right\rceil \leq \left\lceil \frac{n}{b} \right\rceil$ , The

objective function with modified deteriorating rate  $\alpha'_j$  is

$$\begin{aligned} C'_{\max}(S) + \sum_{J_j \in \bar{S}} e_j &= t_0 \prod_{B_i \in T} [1 + \alpha(B_i)]_{\varepsilon'} + \sum_{J_j \in \bar{S}} e_j \\ &\leq t_0 (1 + \varepsilon')^{\left\lceil \frac{|S|}{b} \right\rceil} \prod_{B_i \in T} (1 + \alpha(B_i)) + \sum_{J_j \in \bar{S}} e_j \\ &\leq t_0 (1 + \varepsilon')^{\left\lceil \frac{n}{b} \right\rceil} \prod_{B_i \in T} (1 + \alpha(B_i)) + \sum_{J_j \in \bar{S}} e_j. \end{aligned}$$

From Lemma 2, we have  $(1 + \varepsilon')^{\left\lceil \frac{n}{b} \right\rceil} = \left( 1 + \frac{\frac{\varepsilon}{2}}{\left\lceil \frac{n}{b} \right\rceil} \right)^{\left\lceil \frac{n}{b} \right\rceil} \leq 1 + \varepsilon$  for  $0 \leq \varepsilon \leq 2$ . Then

$$C'_{\max}(S) + \sum_{J_j \in \bar{S}} e_j \leq (1 + \varepsilon) \left( t_0 \prod_{B_i \in T} (1 + \alpha(B_i)) + \sum_{J_j \in \bar{S}} e_j \right) = (1 + \varepsilon) \left( C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j \right),$$

$\forall S \subset J$ .

Note that  $F'^* \leq C'_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$  for  $\forall S \subset J$  and

$F^{r*} = \min_{S \subset J} \left\{ C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j \right\}$ . Thus,  $\frac{F^{r*}}{F^*} \leq 1 + \varepsilon$ . From the discussion of the algorithm,

we know that the time complexity is

$$O\left(nb \sum_{j=1}^n L_j\right) = O\left(\frac{nb \left\lceil \frac{n}{b} \right\rceil \sum_{j=1}^n \log(1 + \alpha_j)}{\varepsilon}\right) = O\left(\frac{nb \left\lceil \frac{n}{b} \right\rceil \log \prod_{j=1}^n (1 + \alpha_j)}{\varepsilon}\right) = O\left(\frac{n^2 b \left\lceil \frac{n}{b} \right\rceil \log(1 + \alpha_{\max})}{\varepsilon}\right).$$

Where  $\alpha_{\max} = \max\{\alpha_j : j = 1, 2, \dots, n\}$ . This completes the proof.

## Conclusion

In this paper, we presented pseudo-polynomial time algorithm and FPTAS for problem  $1|p_j = \alpha_j t, b < n, rej|C_{\max}(S) + \sum_{J_j \in \bar{S}} e_j$ .

For future research, it is worth considering other objective such as  $\sum_{J_j \in S} C_j + \sum_{J_j \in \bar{S}} e_j$ . Another direction for future research is to consider the parallel-machine problems.

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