



Study and Control of a Pumped Storage Hydropower System Dedicated to Renewable Energy Resources

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<https://doi.org/10.18280/jesa.530112>

ABSTRACT

Received: 26 October 2019

Accepted: 28 December 2019

Keywords:

pumped-storage hydropower, renewable energy, permanent machine synchronous generator, power control

The pumped storage hydropower systems are benefits for grid reliability and integration of variable renewable energy, in this context this paper presents the study and control strategy of a pumped storage hydropower (PSH) system based on permanent magnet synchronous machine (PMSM) associated to the renewable energy source. The dynamic behavior of a pump-turbine, including the PMSM with high number of poles, the AC/DC converter and the control of this system, is studied. Also, a control method of the PSH system, which consists of the reversible pump-turbine unit entrained by the PMSM, supplied of the variable power renewable energy source through a power electronic converter. Simulation results obtained on the basis of the dynamic models of the pump-turbine are given, for different operating points, to demonstrate the performance of the proposed system.

1. INTRODUCTION

The increasing penetration of renewable energy sources (RES) in the power system has highlighted the benefits of being able to store energy in a more efficient manner, and the need of holding additional operating reserves to manage the system under more demanding conditions due to the inherent uncertainty and variability of wind and solar power [1, 2].

The increasing penetration of renewable energy sources (RESs) in the power system has highlighted the benefits of being able to store energy in a more efficient manner, and the need of holding additional operating reserves to manage the system under more demanding conditions due to the inherent uncertainty and variability of wind and solar power [1, 3].

A renewed economic and technical interest in energy storage has been observed in recent years because of the increased number of unstable RES. A wide range of energy storage technologies is available today, which provide a large spectrum of performance and capacity for different application purposes [4, 5].

The pumped storage hydropower systems are the most reliable and is the oldest and largest energy storages for accommodating intermittent renewable generators in the power grid [6, 7]. Hydropower is not only environmentally friendly, but also cost-effective [8]. The pumped hydro energy storage (PHES) is a well-established and commercially acceptable technology for utility-scale electricity storage and has been used since as early as the 1890s [9].

Variable speed pump-turbine units have become nowadays-major partner to increase stability of electrical power networks due to their high level of operating flexibility [10, 11]. In addition, pumped-hydro storage facilities can contribute significantly to the load-frequency control in generating mode [12].

Indeed, variable speed pump-turbine units offer several advantages for both pumping and generating modes such as:

possibility of active power control in pumping mode, efficiency increase and wide range of operation in generating mode especially under partial load, network stability improvement by reactive power control and network stability improvement by instantaneous active power injection in the network (flywheel effect).

Extended operating range in pump mode and higher efficiency in turbine mode achievable with variable speed units [10, 13].

This paper points out the advantages of the implementation of variable speed pump-turbines use a PMSM and describes the variable speed technology.

The present work introduced at the pumped-storage hydropower system associated to the renewable energy sources. Which is considered as a promising technology for renewable energy source. A reversible AC pump-turbine unit, based on permanent magnet synchronous machine, is used in the system. The system under study is globally represented by the setup depicted in Figure 1.

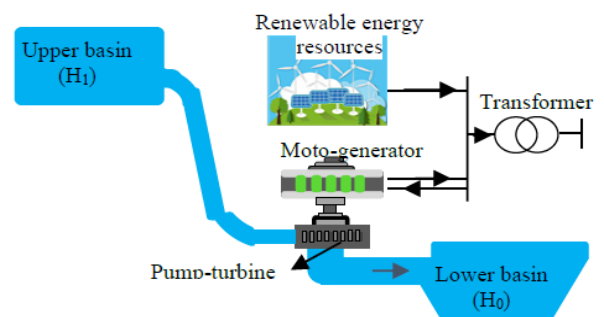


Figure 1. A PHES with RES producing electricity

It combined a pumped hydro storage system with renewable energy source. The RES is connected to the grid via two power

electronics converters with an intermediate DC link bus where is connected a pumped-storage hydropower system. The modeling details of the scheme studied in Figure 1 are described in detail in further sections.

2. MODELING SYSTEM

2.1 Renewable energy source

The power profile provided by the RES is given by the Figure 2. In this proposed hybrid system, the electrical grid is mainly supplied by the RES with fixed power. The excess of energy from the RES is used to pump the water from the lower reservoir to store it in an upper reservoir.

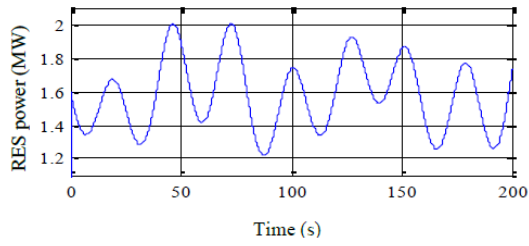


Figure 2. RES power profile

2.2 Mathematical model of PMSM

The PMSM, model in the park reference frame, is described by:

$$\begin{cases} v_d = R_s i_d - p\Omega_w L_q i_q + L_d \frac{di_d}{dt} \\ v_q = R_s i_q + p\Omega_w (L_d i_d + \Phi_f) + L_q \frac{di_q}{dt} \end{cases} \quad (1)$$

where, R_s is the stator winding resistance, p is the pair pole number of the synchronous generator, i_d and i_q are, respectively, the direct and quadratic current, L_d and L_q are respectively, the direct and the quadratic inductance respectively, v_d and v_q are the direct and quadratic voltage and Ω_w is a mechanical speed.

The direct and quadratic magnetic fluxes are given by (the excitation flux Φ_f is constant):

$$\begin{cases} \Phi_d = L_d i_d + \Phi_f \\ \Phi_q = L_q i_q \end{cases} \quad (2)$$

The electromagnetic torque is also expressed as follow:

$$C_{em} = p(\Phi_d i_q - \Phi_q i_d) \quad (3)$$

The active and reactive powers are given according to:

$$\begin{cases} P = v_d i_d + v_q i_q \\ Q = v_q i_d - v_d i_q \end{cases} \quad (4)$$

2.3 Converter modeling

A switching function T_{ij} is defined for each power switch (Figure 3). It represents the ideal commutation and takes the value 1 if the switch is close, 0 when he is open (off):

$$T_{ij} = \begin{cases} 1 & \text{if } T_{ij} \text{ is close} \\ 0 & \text{if } T_{ij} \text{ is open} \end{cases} \quad (5)$$

$i \in \{1,2,3\}$ number of the arm, $j \in \{1,2\}$ number of the switch in the arm.

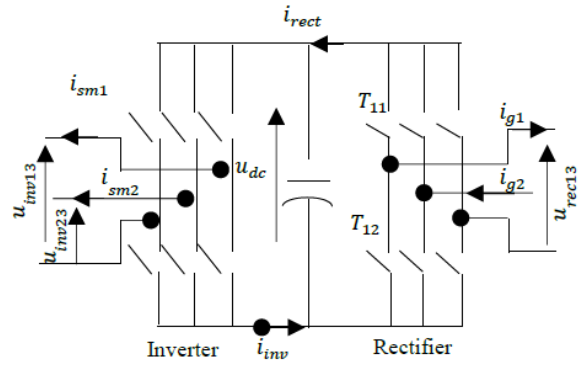


Figure 3. Cascade rectifier-inverter

As ideal, power switches are considered, the switches of the same arm are in complimentary states:

$$T_{i1} + T_{i2} = 1 \quad \forall i \in \{1,2,3\} \quad (6)$$

For both three-phase converters, modulation functions can be defined from the switching functions:

$$m = [m_{13} \ m_{23}] = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} T_{11} \\ T_{21} \\ T_{31} \end{bmatrix} \quad (7)$$

The rectifier leads to the voltages from the capacitor voltage u_{cap} , and the rectifier currents i_{rect} , which circulate in the capacitor from the machine current i_{sm} .

$$\begin{cases} u_{rect} = m_{rect} u_{cap} \\ i_{rect} = m_{rect}^t i_{sm} \end{cases} \quad (8)$$

The three-phase inverter modelled in the same way. It yields the inverter voltages $u_{inv} = [u_{inv13}, u_{inv23}]^T$ from the capacitor voltage and the inverter currents from the line currents $i_{line} = [i_{line1}, i_{line2}]^T$.

$$\begin{cases} u_{inv} = m_{inv} u_{cap} \\ i_{inv} = m_{inv}^t i_{line} \end{cases} \quad (9)$$

2.4 The model of reversible pump turbine

The mathematical model of the pump-turbine describes the relationship between the output mechanical power of the pump-turbine and the guide vane opening. In this paper, the ideal pump-turbine model is used without losses [16, 17]. The transfer function can be written as follows:

$$P_{gp} = \frac{1 - T_w s}{1 + 0.5 T_w s} G \quad (10)$$

where, p_{gp} : The pump-turbine mechanical output power; G : guide vane opening and T_w : The water starting time.

3. CONTROL THE HPS

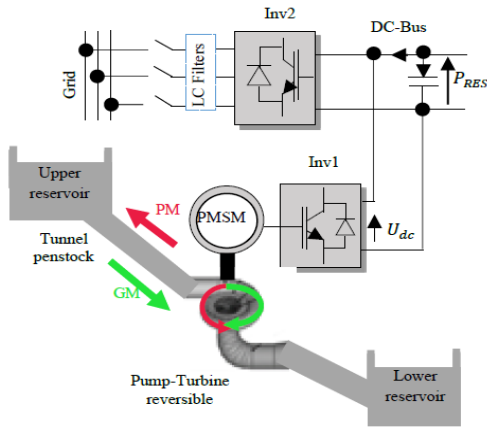


Figure 4. Study system global scheme

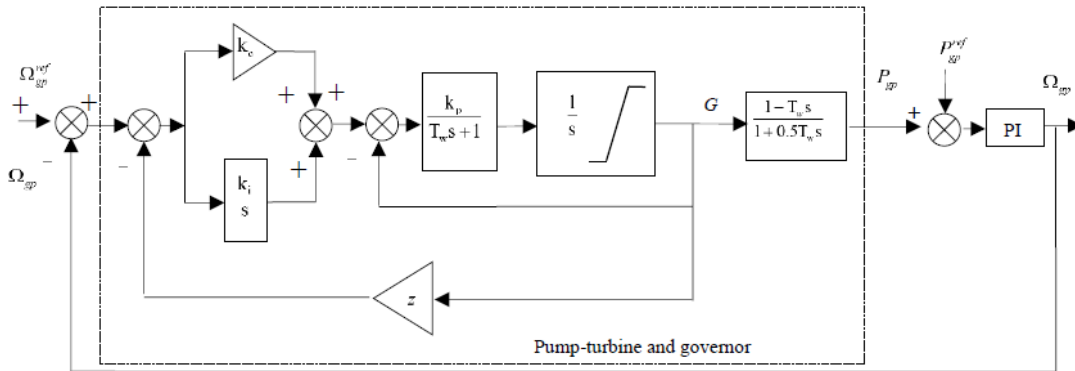


Figure 5. Structure of the servomechanism and PI controller

3.2 Control strategy for the PSH system

Exceeded energy, when available, is stored as potential energy in the pumped-hydro storage system by pumping water from a lower altitude to a higher altitude. When the production is not sufficient, this energy is reconverted into the electrical form and transmitted to the DC bus and allows regulating electrical power delivered into the grid. The fundamental control diagram is given in Figure 6.

When the P_{RES} is less than the P_g^{ref} generation mode work. The PHES will convert its present operation mode immediately, and then adjust the speed of the reversible pump-turbine to the maximum in order to reduce the large fluctuation.

When the P_{RES} is higher than the P_g^{ref} pumping mode work.

The global control scheme of this part is given in Figure 4.

The model of HPS is mainly composed of Pumped storage hydro-plants (a reversible pump turbine model, a PMSM model (520kW), a RES with a maximum power of 2MW. and control system model of the converter. The reversible pump turbine provides mechanical torque for PMSM. The associated control structure is based on the Park model of the PMSM (d, q reference frame) the field-oriented control is used to control of the generator.

3.1 Generating mode

In generating mode, the strategy is presented in Figure 5 consist of a PI type regulator whose output acts on the guide vane opening through a servomotor. The power set point is imposed by the grid conditions and the speed set point is calculated by a speed optimizer in order to maximize the turbine efficiency. This speed optimizer is a look-up table defined as a surface representing the optimal speed as a function of the power and the mass flow rate Q_v .

The transfer function of the PI regulator is given by:

$$G_{PI}(s) = \frac{1}{z} \cdot \frac{1 + \frac{K_c}{K_i} s}{1 + \frac{1}{K_i} \left(\frac{1}{z} + K_c \right) s} \quad (11)$$

where, K_c : proportional gain, K_i : integral gain, z : the droop, K_p : the gain of the pilot valve and T_p : the time constant of the pilot valve (s).

The strategy in pumping mode consists of a generator power controller similar to the one developed for the strategy in generating mode and of a guide vane opening optimization [15].

The PHES will adjust the speed of the reversible pump-turbine, meantime modifying the scheduled pumping capacity in this hour period.

The control structure of the PMSM is based on the Park model (d, q frame) and the field orientation is achieved by regulating the direct current component i_d^{ref} to zero.

The reference value P_{gp}^{ref} of the active power of the pumped-hydro storage system is determined by:

$$\begin{cases} P_{gp}^{ref} = P_{RES} - P_g^{ref} \\ P_{gp}^{ref} = \eta_{gp} \cdot P_{gp} \end{cases} \quad (12)$$

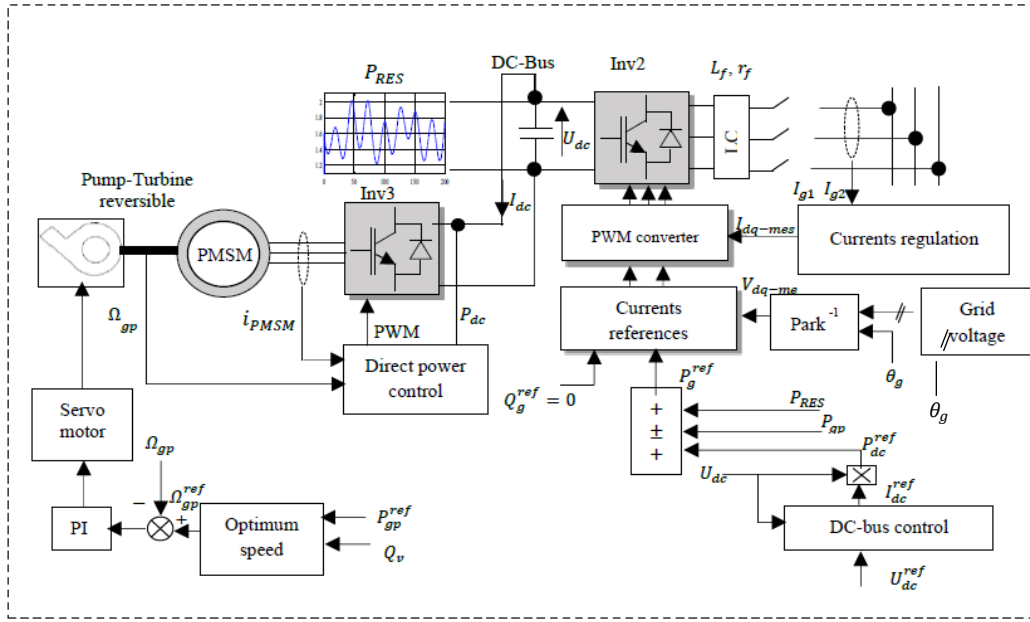


Figure 6. Control of the HPS study

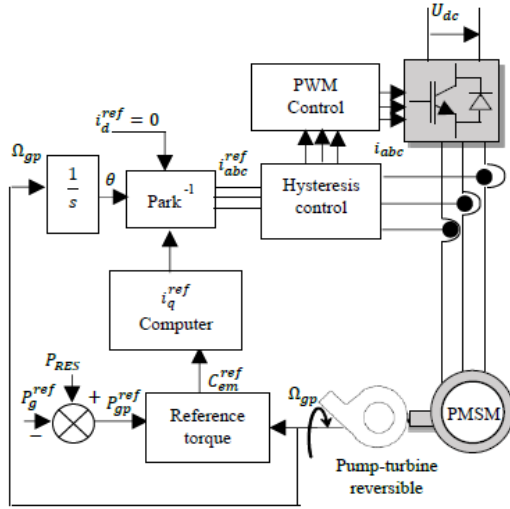


Figure 7. Control bloc diagram of the hydroelectric plant

If the P_{RES} is less than the P_g^{ref} generation mode work. The PHES will convert its present operation mode immediately, and then adjust the speed of the reversible pump-turbine to the maximum in order to reduce the large fluctuation. Else if, the P_{RES} is higher than the P_g^{ref} pumping mode work. The PHES will adjust the speed of the reversible pump-turbine, meantime modifying the scheduled pumping capacity in this hour period.

The control structure of the PMSM is based on the Park model (d, q frame) and the field orientation is achieved by regulating the direct current component i_d^{ref} to zero.

The reference value P_{gp}^{ref} of the active power of the pumped-hydro storage system is determined by:

$$\begin{cases} P_{gp}^{ref} = P_{RES} - P_g^{ref} \\ P_{gp}^{ref} = \eta_{gp} \cdot P_{gp} \end{cases} \quad (13)$$

where, P_{gp}^{ref} being the reference grid active power, fixed to the value 1.6 MW, P_{RES} the optimal aerodynamic power generated, and η_{gp} the power hydroelectric plants efficiency. The

machine-side converter allows the control of the speed of rotation of the group in the two operating modes (turbine mode and pump mode); whereas the converter on the network side transfers, the power produced to the grid in the turbines mode and supplies the DC-Bus for motor operation in pumping mode. The overall scheme of the control of the micro-hydropower is shown in Figure 7.

3.3 PMSM currents regulation

PMSM currents are regulated by hysteresis controllers, which allow keeping the current wave into range defined around the reference value. When current wave reached the band limits, the hysteresis controller generates a logic signal (0 or 1) (Figure 8). So, for (j=1, 2, 3).

We have:

$$\begin{cases} F_j = 1 & \text{if } i_{mj}^{ref} - i_{mj} \geq \Delta i \\ F_j = 1 & \text{if } i_{mj}^{ref} - i_{mj} < \Delta i \end{cases} \quad (14)$$

With Δi is the hysteresis band defined in the controller.

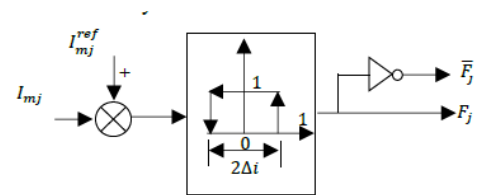


Figure 8. Plant Hysteresis regulation principal

3.4 DC-bus regulation

The electrical equations for the circuit are given by:

$$\frac{dU_{dc}}{dt} = \frac{1}{C_{dc}} I_c \quad (15)$$

With:

$$I_c = I_{dc} - I_{ond} \quad (16)$$

The direct inversion of equation (15) makes it possible to obtain the reference current upstream of the inverter. I_{ond}^{ref} which is expressed as follows:

$$I_{ond}^{ref} = I_{dc} - PI(s) \left(U_{dc}^{ref} - U_{dc} \right) \quad (17)$$

where, $PI(s)$ is the transfer function of the PI regulator and U_{dc}^* is the reference of the DC voltage. The transfer function between the I_{ond}^{ref} and I_{dc} currents is considered of the first order with a very high dynamic for the synthesis of the corrector; because the dynamics of the current is generally faster than that of the voltage.

3.5 Grid currents regulation

The reference reactive power is imposed at zero, in order to operate at a factor of unitary power of the grid side. The Figure 9 represented the control of grid side converter, has for objective to obtain current and voltage with acceptable wave form and to ensure unitary power factor.

The electrical equations downstream the converter can be expressed as follows:

$$\begin{cases} I_{g1} = \frac{1}{r_f + L_f s} (V_{inv1} + V_{g1}) \\ I_{g2} = \frac{1}{r_f + L_f s} (V_{inv2} + V_{g2}) \end{cases} \quad (18)$$

The use of mathematical model of converter (with assumption of an equilibrate voltage system) allows expressing simple voltages reference as follows [18, 19]:

$$\begin{pmatrix} V_{inv1}^{ref} \\ V_{inv2}^{ref} \end{pmatrix} = \begin{pmatrix} V_{f2}^{ref} \\ V_{f2}^{ref} \end{pmatrix} + \begin{pmatrix} V_{g1} \\ V_{g2} \end{pmatrix} \quad (19)$$

With PI regulation of grid currents, we obtained the reference voltages v_{f1}^{ref} and v_{f2}^{ref} (Figure9) [16, 17]:

$$\begin{pmatrix} V_{f1}^{ref} \\ V_{f2}^{ref} \end{pmatrix} = PI(s) \begin{pmatrix} I_{g1}^{ref} & I_{g1} \\ I_{g2}^{ref} & I_{g2} \end{pmatrix} \quad (20)$$

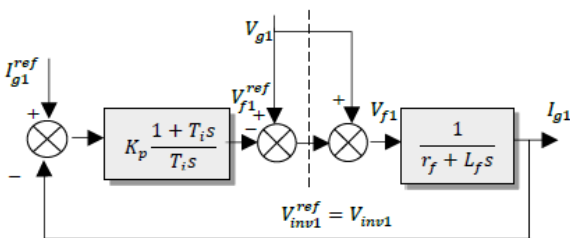


Figure 9. Grid current regulation

4. SIMULATION RESULTS AND DISCUSSION

Tables 1-4 give the parameters for the reversible pump-turbine, the PMSM and the electrical grid. The studied system, shown in Figure 7, is implemented in the Matlab\Simulink software environment. The results of simulation are obtained for active power reference $p_g^{ref} = 1.6MW$, the reactive power reference $Q_g^{ref} = 0$ and the typical RES power given in Figure 2.

Table 1. Basic parameters of Pump turbine hydropower

Designation	Value
nominal power	520 kW
Rate speed	360 rpm
Efficiency	0.76

Table 2. Basic parameters of PMSM

Designation	Value
Frequency	50 Hz
Stator winding resistance	12 mΩ
Direct cyclic inductance	0.13 mH
Quadratic cyclic inductance	0.13 mH
Excitation Flux	2.5Wb

Table 3. Basic parameters DC-Bus, Filter and grid

Designation	Value
DC-Bus voltage	1.5 kV
DC-Bus capacitor	0.015 F
Inductance filter	0.002 H
Resistor filter	0.01Ω
Grid voltage (Rms)	690 V

Table 4. Value of the feedback gains PI

Designation	Value
Proportional gain	2.15
Integral gain	0.43

Figures (10-12) show the speed rotation, the guide vane opening and the power in generating mode.

The guide vane opening increases along with the increase of power, there is a small fluctuation, which is caused by the power fluctuation.

The pumped-storage hydropower power follows the variation in according to the active power transmitted to the DC-bus as results, reversible pump-turbine speed slowdown or accelerate in order to return or store energy, respectively.

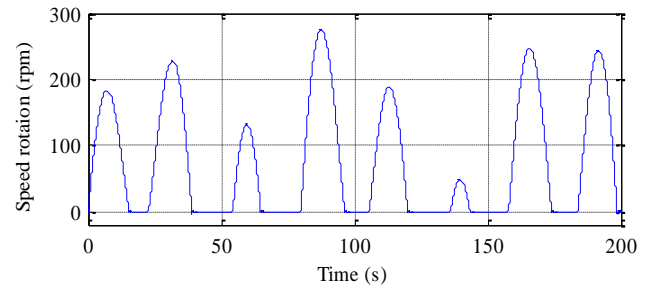


Figure 10. Speed rotation in generation mode

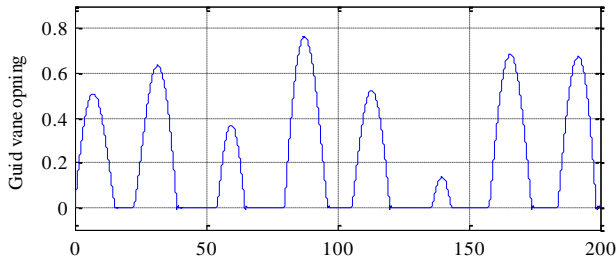


Figure 11. Guide vane opening in generating mode

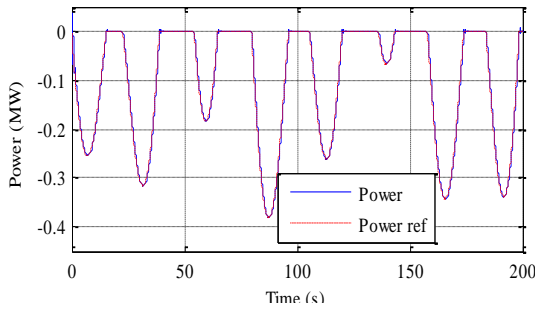


Figure 12. Power in generating mode

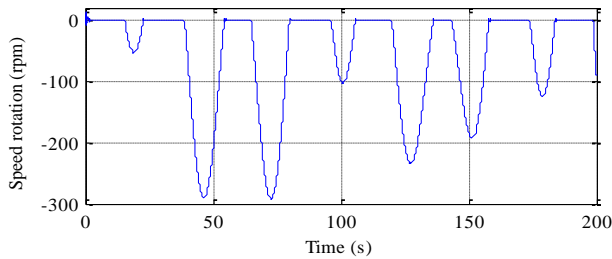


Figure 13. Speed rotation in generation mode

The speed rotation, the guide vane opening and the power in pumping mode are given by the Figures (13-15).

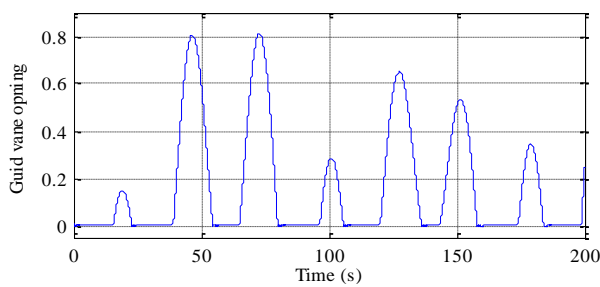


Figure 14. Guide vane opening in generating mode

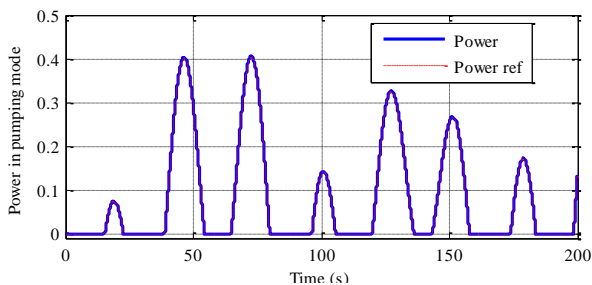


Figure 15. Power in pumping mode

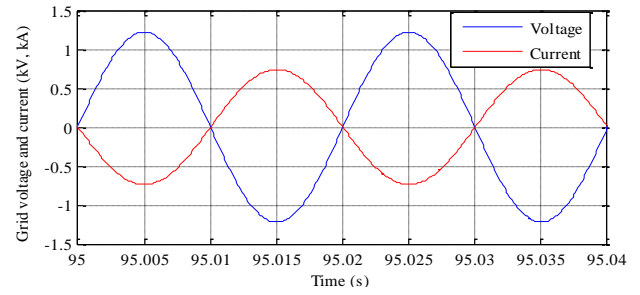


Figure 16. Grid voltage and current

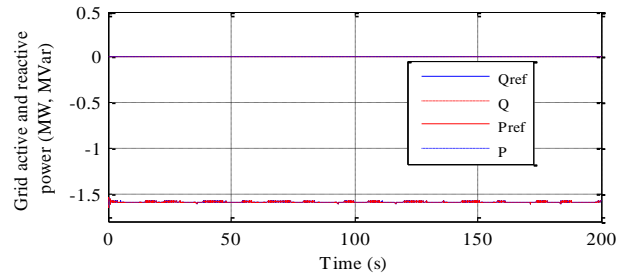


Figure 17. Grid active and reactive powers

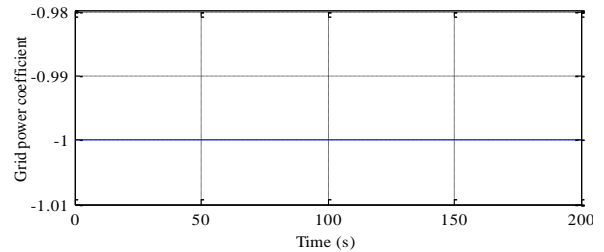


Figure 18. Grid power coefficient

The guide vane opening increases along with the increase of power. The Pumped-Storage power follow the variation in according to the active power transmitted to the DC bus as results.

The results of simulation for both modes evidence the performance of the variable speed hydropower plant, showing a dynamic response excellence when the system switches from the generate mode ($\Omega_{gp} > 0$) to the pumping mode ($\Omega_{gp} < 0$). Ensure the stability of the speed control, when the reversible pump-turbine units operating state changes, in order to avoid emitted active power fluctuations of the RES. The power variation for both modes follows the variation of the guide vane opening, that assuring more efficient management of available RES.

The response is almost instantaneous compared to the conventional fixed speed reversal mode where the response time can exceed a few minutes (due to the complex reversal procedure).

Figure 16 gives the grid voltage and current with sinusoidal wave form at constant frequency, the use of hydroelectric allowed providing a regular and smooth active power to the electrical grid and compensates fluctuations in Renewable Energy Source by controlling the voltage and the frequency (50Hz) of the electrical network.

Figure 17 shows the active and reactive powers, the grid active power remains constant at 1.6 MW and the grid reactive power is equal to zero, which corresponds to unitary power factor in Figure 18.

5. CONCLUSION

The pumped storage hydropower associated to the renewable energy source has been studied in this paper. The first part is devoted to the analysis, modeling and simulation of each part of the system. In the second part, the PHES schema including a PMSM using a reversible pump-turbine unit is detailed. A dynamic response and governor tuning of pumped hydroelectric energy storage has been developed and studied.

The simulation results have confirmed the reversible pump-turbine operation in that variable speed technology allows for rapid transition between the two operating modes. This advantage of the pumped hydroelectric energy storage system offers a high performance for the compensation of the power fluctuation of renewable energy sources.

The variable speed technology in pump-turbines permits the energy storage and production with a fast reactivity (seconds), the grid frequency regulation (in both regimes pump and turbine) and the optimization of the efficiency of the hydraulic power plants.

The variable speed technology in pump-turbines is a breakthrough technology that starts to be implemented, due to the new energy market configuration.

ACKNOWLEDGEMENTS

We would like to thank the Directorate general for scientific research and technological development for funding our Laboratory.

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NOMENCLATURE

PSH	Pumped storage hydropower
PMSM	permanent magnet synchronous machine
HPS	Hybrid power system
RES	Renewable Energy Source
AC/DC	Converters
PV	Photovoltaic energy
P_{gp}	power of pump-turbine unit
P_{gp}^{ref}	Reference power of the pump-turbine
P_{RES}	Power of the RES
P_{dc}	Power of DC-voltage
P_{dc}^{ref}	Reference power of the CD voltage
Q_g^{ref}	Reference power of the grid
Q	grid reactive power
P	grid active power
P^{ref}	grid active reference power
C_{em}	Electromagnetic torque
v_d	Direct voltage
v_q	Quadratic voltage
Q_g^{ref}	Reference power of the grid
Q	grid reactive power
i_d	Direct current
i_q	Quadratic current
R_s	stator winding resistance

L_f	Inductance filter
R_f	Resistor filter
H_1	Upper level
H_0	Lower level
T_{ij}	witching function
G	Guide vane opening
T_w	Water starting time
U_{dc}	DC voltage
i_d	Direct current
K_c	Proportional gain
K_i	Integral gain
K_p	Proportional gain of pilot valve
z	Droop coefficient
I_{g1}	Grid current
I_{g2}	Grid current
V_{g1}	Grid voltage
V_{g2}	Grid voltage

Greek symbols

η_{gp}	Efficiency of the pump-turbine unit
Φ_f	Excitation flux
Φ_d	Direct magnetic fluxes
Φ_q	Quadratic magnetic fluxes
Ω_{gp}^{ref}	Mechanical speed reference of the pump-turbine unit
Ω_{gp}	Mechanical speed of the pump-turbine unit
Ω_w	mechanical speed of the PMSM