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Novel Solutions to Fractional Nonlinear Equations for Crystal Dislocation and Ocean Shelf Internal Waves via the Generalized Bernoulli Equation Method



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https://doi.org/10.18280/mmep.100312	ABSTRACT
Received: 10 January 2023	The nonlinear space and time fractional (2+1)-dimensional cubic Klein-Gordon (cKG)

Accepted: 23 March 2023

Keywords:

fractional partial differential equations, generalized Bernoulli equation method, traveling wave solution, fractional cubic Klein Gordon equation, fractional Gardner-KP equation The nonlinear space and time fractional (2+1)-dimensional cubic Klein-Gordon (cKG) equation and the nonlinear space and time fractional (2+1)-dimensional Gardner-KP (GKP) equation are applied to model crystal dislocation and internal waves on ocean shelves, respectively. To solve these equations, the fractional cKG and GKP equations are first converted into nonlinear ordinary differential equations (ODEs) using wave transformation and Jumarie's Riemann-Liouville derivative. The solution is then expressed as a finite series, and this approach is combined with the generalized Bernoulli equation method. Exact traveling wave solutions are obtained in the form of exponential functions, hyperbolic functions, and rational functions, which ultimately give rise to physical waves. These waves manifest in various forms, such as kink, periodic, and solitary waves, and are represented by two-dimensional and three-dimensional graphical illustrations.

1. INTRODUCTION

Nonlinear phenomena encompass a diverse range of applications, spanning fields such as atmospheric science, condensed matter physics, theoretical particle physics, and cosmic structures. These phenomena are particularly relevant in disciplines including fluid mechanical engineering, electrical engineering, solid-state physics, plasma physics, plasma waves, chemical physics, and optical fibers. Nonlinear waves and the structures they elucidate are central to contemporary theories across various domains. Nonlinear partial differential equations (PDEs) play a critical role in characterizing nonlinear wave phenomena, accounting for dispersion, dissipation, convection, and response. Current research efforts are primarily focused on exploring exact or numerical solutions to leverage the insights derived from these studies. Investigating the precise traveling wave solutions of nonlinear fractional PDEs is crucial for deepening our understanding of the underlying factors.

A myriad of methods has been employed to solve nonlinear fractional PDEs, including the Riccati-Bernoulli sub-ODE method [1, 2], Kudyashov [3, 4], first integral method [5, 6], generalized Kudryashov method [7, 8], modified Kudryashov method [9, 10], functional variable method [11, 12], G'/G-expansion method [13, 14], fractional sub-equation method [15, 16], and simple equation method [17, 18].

In 2006, the Riemann-Liouville derivative of the Jumarie equation [19] was described as follows:

$$D_{t}^{\alpha}\Upsilon(t) = \begin{cases} \Upsilon(t) & , \alpha = 0\\ \frac{d}{dt} \int_{0}^{t} \frac{[\Upsilon(\delta) - \Upsilon(0)]}{(t - \delta)^{\alpha}} d\delta \\ \frac{d}{t^{n}} D_{t}^{\alpha - n}\Upsilon(t) & , 0 < \alpha < 1\\ \frac{d^{n}}{dt^{n}} D_{t}^{\alpha - n}\Upsilon(t) & , n \le \alpha < n + 1, \\ n \ge 1, \end{cases}$$
(1)

where, a is an order of the fractional derivative.

In 2009, the following was presented as the Riemann-Liouville derivative of the Jumarie [20]:

$$D_{t}^{\alpha}t^{\varphi} = \frac{\Gamma(\varphi+1)}{\Gamma(\varphi-\alpha+1)}t^{\varphi-\alpha}, \ \varphi \ge 0,$$
(2)

$$D_{t}^{\alpha} \Big[\Upsilon(t) \Psi(t) \Big] = \Upsilon(t) D_{t}^{\alpha} \Psi(t) + \Psi(t) D_{t}^{\alpha} \Upsilon(t), \qquad (3)$$

$$D_{t}^{\alpha} \Upsilon \Big[\Psi (t) \Big] = D_{\Psi}^{\alpha} \Upsilon \Big[\Psi (t) \Big] \Big[\Psi' (t) \Big]^{\alpha}$$

= $\Upsilon'_{\Psi} \Big[\Psi (t) \Big] D_{t}^{\alpha} \Psi (t).$ (4)

The (2+1)-dimensional cKG equation is one of the secondorder non-linear evolution equations. This equation has been employed to form a variety of different non-linear phenomena [21], including the propagation of crystal dislocation, the action of elementary particles, and the proliferation of fluxions in Josephson junctions, to name a few examples. The cKG equation has a non-linearity that indicates that the constant value with $\omega = \omega(x, y, t)$ and β , ε are not zero, as seen below:

$$\omega_{xx} + \omega_{yy} - \omega_{tt} + \beta\omega + \varepsilon\omega^3 = 0.$$
 (5)

The exact solution [21] of Eq. (5) is:

$$\omega = \pm I \sqrt{\frac{\beta}{\varepsilon}} \left(1 - \frac{2b_1 \cosh(b_2) + \sinh(b_2)}{(b_1 - 2a_2\alpha)\cosh(b_2) + (b_1 + 2a_2\alpha)\sinh(b_2)} \right), \quad (6)$$

where, $b_1 = a_1(\lambda^2 - 2), b_2 = \sqrt{\frac{\alpha}{-2(\lambda^2 - 2)}}(x + y - \lambda t)$ and a_1 , a_2 are constants of integration.

On the ocean shelf, powerful nonlinear internal waves are described by the (2+1) dimensional GKP Equation [22]. This is the form of the non-linear positive GKP Equation [23] of the fourth-order with $\omega = \omega(x, y, t)$:

$$\left(\omega_t + 6\omega\omega_x + 6\omega^2\omega_x + \omega_{xxx}\right)_x + \omega_{yy} = 0.$$
(7)

The explicit form of exact travelling wave solutions of positive GKP Equation [23] is:

$$\omega = \frac{4(c+1)e^{\sqrt{-c-1\xi}}}{4ce^{2\sqrt{-c-1\xi}} - 4e^{\sqrt{-c-1\xi}} - 1},$$
(8)

where, $\xi = \int \frac{d\omega}{\varphi}$, $\varphi = \frac{d\omega}{d\xi}$ and *c* is wave speed.

The fractional cKG equation and the fractional GKP equation have both been solved in this article by using Jumarie's Riemann-Liouville derivative and the generalized Bernoulli equation method. We were able to get 13 solutions for each equation, and these solutions came in the form of hyperbolic functions, exponential functions, and rational functions. Using two-dimensional graphs and three-dimensional graphs, we were able to demonstrate the exact solutions as well as the physical waves which are kink waves, solitary waves and periodic waves. These results can be compared with the numerical solutions. Moreover, it can also be applied to initial and boundary value problems. Finding the traveling wave solutions in this research demonstrates the efficiency of the generalized Bernoulli equation method for solving the non-linear fractional PDEs.

2. ALGORITHM OF THE GENERALIZED BERNOULLI EQUATION METHOD

We will go through the generalized Bernoulli equation method for solving fractional PDEs in this section. The fundamental form of fractional PDEs [24] may be illustrated as:

$$F\left(\omega, D_x^{\alpha}\omega, D_y^{\alpha}\omega, D_t^{\alpha}\omega, D_x^{2\alpha}\omega, D_y^{\alpha}D_x^{\alpha}\omega, D_t^{\alpha}D_x^{\alpha}\omega, \ldots\right) = 0,$$
(9)

where, t > 0 and $0 \le \alpha \le 1$.

The steps needed to carry out this procedure are outlined in the following instructions [24]:

Step 1: Wave transformation

The traveling wave solution to fractional partial differential equations is a solution that meets certain conditions.

$$\omega(x, y, t) = \Theta(\delta), \delta = \frac{rx^{\alpha}}{\Gamma(\alpha + 1)} + \frac{sy^{\alpha}}{\Gamma(\alpha + 1)} - \frac{ct^{\alpha}}{\Gamma(\alpha + 1)}, \quad (10)$$

where, r and s are considered to be constants, c is also considered to be a constant, but this time it relates to the speed of the wave. Eq. (9) is converted into an ODE by Eq. (10):

$$H\left(\Theta,\Theta',\Theta'',\Theta''',\ldots\right) = 0,\tag{11}$$

where, *H* is a polynomial in $\Theta(\delta)$ and its derivatives. Step 2: Solution supposition We use the finite series to work out the solution to Eq. (11), and then we *write* it down:

$$\Theta(\delta) = \sum_{i=0}^{K} b_i G^i(\delta), \qquad (12)$$

where, b_i are non-zero constants and $G(\delta)$ are variables that are dependent on using the method of the generalized Bernoulli equation, which states as follows:

$$G'(\delta) = \eta G(\delta) + \xi G^2(\delta), \qquad (13)$$

where, η , ξ are the constants that are not zero in the expression. The answers to Eq. (13) may be subdivided into 13 different situations [25].

For real and non-zero η , $\eta^2 > 0$ and $\zeta \neq 0$ the solutions to Eq. (13) are:

$$G_{1}(\delta) = \frac{-\eta - \eta \tanh\left(\frac{\eta\delta}{2}\right)}{2\xi},$$
(14)

$$G_2(\delta) = \frac{-\eta - \eta \coth\left(\frac{\eta\delta}{2}\right)}{2\xi},\tag{15}$$

$$G_3(\delta) = \frac{-\eta - \eta \tanh(\eta \delta) \mp i\eta \operatorname{sech}(\eta \delta)}{2\xi}, \quad (16)$$

$$G_4(\delta) = \frac{-\eta - \eta \coth(\eta \delta) \mp \eta \operatorname{csch}(\eta \delta)}{2\xi}, \qquad (17)$$

$$G_5(\delta) = \frac{-2\eta - \eta \tanh\left(\frac{\eta\delta}{4}\right) - \eta \coth\left(\frac{\eta\delta}{4}\right)}{4\xi}, \qquad (18)$$

$$G_6(\delta) = \frac{\eta \sqrt{Q^2 + R^2} - \eta Q \cosh(\eta \delta)}{2\xi Q \sinh(\eta \delta) + 2\xi R} - \frac{\eta}{2\xi},$$
 (19)

$$G_7(\delta) = \frac{-\eta \sqrt{R^2 - Q^2} - \eta Q \sinh(\eta \delta)}{2\xi Q \cosh(\eta \delta) + 2\xi R} - \frac{\eta}{2\xi}, \qquad (20)$$

where, Q and \underline{R} are two non-zero real constant that satisfy $R^2-Q^2>0$.

$$G_8(\delta) = \frac{\pm \eta e^{\eta \delta}}{\xi \mp \xi e^{\eta \delta}},\tag{21}$$

$$G_9(\delta) = \frac{\pm \eta e^{\eta \delta}}{\xi i \mp \xi e^{\eta \delta}},\tag{22}$$

$$G_{10}(\delta) = \frac{\eta \sqrt{Q^2 - R^2} \pm \eta \left(Q e^{\eta \delta} - iR\right)}{\mp \xi Q \left(e^{\eta \delta} - e^{-\eta \delta}\right) \pm 2\xi iR},$$
(23)

where, Q and R are two non-zero real constant that satisfy $Q^2 - R^2 > 0$.

$$G_{11}(\delta) = \frac{-\eta \phi e^{\eta \delta}}{\xi + \xi \phi e^{\eta \delta}},$$
(24)

$$G_{12}(\delta) = \frac{-\eta e^{\eta \delta}}{\xi \phi + \xi e^{\eta \delta}},$$
(25)

where, ϕ is an arbitrary constant.

For $\eta=0$ and $\xi\neq 0$ and arbitrary constant ψ , the solution to Eq. (13) is:

$$G_{13}(\delta) = \frac{-1}{\xi \delta + \psi}.$$
 (26)

Step 3: Finding the integer K

In order to get the integer K in Eq. (12), you must first strike a balance between the terms for the highest order derivative and the non-linear terms.

Step 4: Solution obtaining

Discover the values of the parameters b_i , i=1, 2, 3, ..., n and c by summing the coefficients of all expressions that have the same order as $G^i(\delta)$ and then setting those coefficients to zero. As a consequence of this, we make up the analytical solutions to Eq. (9).

Solving the two non-linear space-time fractional equations that are presented below allows us to show the generalized Bernoulli equation method.

3. APPLICATIONS

Solving the two non-linear space-time fractional equations that are presented below allows us to show the generalized Bernoulli equation method.

3.1 The non-linear space and time fractional of (2+1)dimensional cKG equation

The results of applying the non-linear space and time fractional cKG equation to traveling waves are shown below:

$$D_x^{2\alpha}\omega + D_y^{2\alpha}\omega - D_t^{2\alpha}\omega + \beta\omega + \varepsilon\omega^3 = 0, \qquad (27)$$

when, $t \ge 0$, $0 \le \alpha \le 1$, $\omega = \omega(x, y, t)$ and the value of β , ε are constants. Taking the assumption that $\omega(x, y, t) = \Theta(\delta)$ is the correct result and applying transformation:

$$\delta = \frac{rx^{\alpha}}{\Gamma(\alpha+1)} + \frac{sy^{\alpha}}{\Gamma(\alpha+1)} - \frac{ct^{\alpha}}{\Gamma(\alpha+1)},$$
(28)

where, the constants r, s and c do not have the value zero. Eq. (28) was used to develop an ODE:

$$r^{2}\Theta'' + s^{2}\Theta'' - c^{2}\Theta'' + \beta\Theta + \varepsilon\Theta^{3} = 0.$$
⁽²⁹⁾

Eq. (10) was the structure that was used in order to provide the solution to the issue by using the generalized Bernoulli equation method. After that, we made certain that the highest order derivative and the non-linear components of Eq. (29) were in balance with one another. Thus K=1. In the end, Eq. (12) was transformed into:

$$\Theta(\delta) = b_0 + b_1 G(\delta). \tag{30}$$

Eq. (30) will take the place of Eq. (29) in this application. In order to make each coefficient equal to zero, we collected all of the terms that belonged to the same power of $G(\delta)$, and then we did the following:

$$G^0(\delta) : b_0 \beta + b_0^3 \varepsilon = 0, \qquad (31)$$

$$G^{l}(\delta) : b_{l}r^{2}\eta^{2} + b_{l}s^{2}\eta^{2} - b_{l}c^{2}\eta^{2} + b_{l}\beta + 3b_{0}^{2}b_{l}\varepsilon = 0, \quad (32)$$

$$G^{2}(\delta) : 3b_{1}r^{2}\eta\xi + 3b_{1}s^{2}\eta\xi - 3b_{1}c^{2}\eta\xi + 3b_{0}b_{1}^{2}\varepsilon = 0, \quad (33)$$

$$G^{3}(\delta) : 2b_{l}r^{2}\xi^{2} + 2b_{l}s^{2}\xi^{2} - 2b_{l}c^{2}\xi^{2} + b_{l}^{3}\varepsilon = 0.$$
(34)

After working out the solution to the system of Eqns. (31)-(34), we obtain:

$$b_0 = \pm \sqrt{-\frac{\beta}{\varepsilon}},\tag{35}$$

$$b_{1} = \pm \xi \sqrt{-\frac{2(r^{2} + s^{2} - c^{2})}{\varepsilon}},$$
(36)

$$c = \pm \frac{\sqrt{r^2 \eta^2 + s^2 \eta^2 - 2\beta}}{\eta}.$$
 (37)

Eqns. (14)-(26), (28), and (35)-(37) provide for the representation of the exact traveling wave solutions of the nonlinear space-time fractional cKG equations in a total of 13 different cases which are distinct from the one that was found in the first solution indicated in Eq. (6).

For real and non-zero η , $\eta^2 > 0$ and $\xi \neq 0$ a and let $b_1 = \pm \xi \sqrt{-\frac{2(r^2 + s^2 - c^2)}{\varepsilon}}$, we obtained:

$$\omega_{\rm l} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{b_{\rm l}}{2\xi} \left(-\eta - \eta \tanh\left(\frac{\eta\delta}{2}\right)\right),\tag{38}$$

$$\omega_2 = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{b_1}{2\xi} \left(-\eta - \eta \coth\left(\frac{\eta\delta}{2}\right)\right),\tag{39}$$

$$\omega_3 = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{b_1 \left(-\eta - \eta \tanh\left(\eta \delta\right) \mp i\eta \operatorname{sech}\left(\eta \delta\right)\right)}{2\xi}, \quad (40)$$

$$\omega_4 = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{b_1 \left(-\eta - \eta \coth(\eta \delta) \mp \eta \operatorname{csch}(\eta \delta)\right)}{2\xi}, \quad (41)$$

$$\omega_{5} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{b_{1}}{4\xi} \left(-2\eta - \eta \tanh\left(\frac{\eta\delta}{4}\right) - \eta \coth\left(\frac{\eta\delta}{4}\right) \right), \quad (42)$$

$$\omega_{6} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + b_{1} \left(\frac{\eta \sqrt{Q^{2} + R^{2}} - \eta Q \cosh(\eta \delta)}{2\xi Q \sinh(\eta \delta) + 2\xi R} - \frac{\eta}{2\xi} \right), \quad (43)$$

$$\omega_{7} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + b_{1} \left(\frac{-\eta \sqrt{R^{2} - Q^{2}} - \eta Q \sinh(\eta \delta)}{2\xi Q \cosh(\eta \delta) + 2\xi R} - \frac{\eta}{2\xi} \right), \quad (44)$$

where, Q and R are two non-zero real constant that satisfy $R^2 - Q^2 > 0$.

$$\omega_8 = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{\pm b_1 \eta e^{\eta \delta}}{\xi \mp \xi e^{\eta \delta}}, \qquad (45)$$

$$\omega_9 = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{\pm b_1 \eta e^{\eta \delta}}{\xi i \mp \xi e^{\eta \delta}}, \qquad (46)$$

$$\omega_{10} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + b_1 \frac{\eta \sqrt{Q^2 - R^2}}{\mp \xi Q \left(e^{\eta \delta} - e^{-\eta \delta}\right) \pm 2\xi i R}, \qquad (47)$$

where, Q and R are two non-zero real constant that satisfy $Q^2 - R^2 > 0$.

$$\omega_{11} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{-b_1 \eta \phi e^{\eta \delta}}{\xi + \xi \phi e^{\eta \delta}}, \qquad (48)$$

$$\omega_{12} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{-b_1 \eta e^{\eta \delta}}{\xi \phi + \xi e^{\eta \delta}}, \qquad (49)$$

where, ϕ is an arbitrary constant.

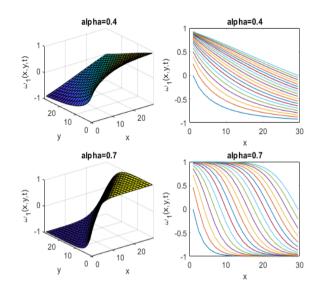
For η =0 and $\xi \neq 0$ and arbitrary constant ψ :

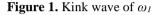
$$\omega_{13} = \pm \sqrt{-\frac{\beta}{\varepsilon}} + \frac{-b_1}{\xi \delta + \psi}, \qquad (50)$$

where,
$$\delta = \frac{rx^{\alpha}}{\Gamma(\alpha+1)} + \frac{sy^{\alpha}}{\Gamma(\alpha+1)} \mp \frac{t^{\alpha}\sqrt{r^2\eta^2 + s^2\eta^2 - 2\beta}}{\eta\Gamma(\alpha+1)}.$$

We have presented some physical graphs which are comparisons between α =0.4 and α =0.7. Figures 1, 2, 3 and 4 present the physical graphs of Eqns. (38), (39), (42) and (45) respectively when we set the parameters β =1, ε =-1, r=-1, s=1, η =1, ξ =1, t=100, 1≤x≤30, 1≤y≤30. We set: β =1, ε =-1, r=-1, s=1, η =1.2, ξ =1, t=100, 1≤x≤30, 1≤y≤30 in Eq. (41) which shown by Figure 5. When we substitute β =1, ε =-1, r=-1, s=1, η =1, ξ =1, t=100, Q=1, R=2, 1≤x≤30, 1≤y≤30 into Eqns. (43) and (44), the physical graphs are presented as Figures 8 and 9 when β =1, ε =-1, r=-1, s=1, η =1, ξ =1, t=100,

 $\phi=1, 1 \le x \le 30, 1 \le y \le 30$ are substituted into Eqns. (48) and (49). Substituting $\beta=1, \epsilon=-1, r=-1, s=1, \eta=1, \xi=1, t=100, \psi=1, 1 \le x \le 30, 1 \le y \le 30$ into Eq. (50), we get the physical graphs shown in Figure 10.





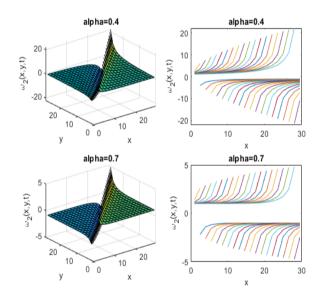


Figure 2. Solitary wave of ω_2

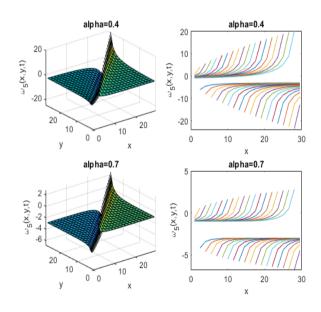


Figure 3. Solitary wave of ω_5

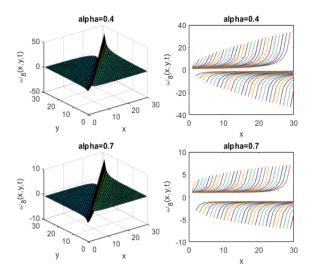


Figure 4. Solitary wave of ω_8

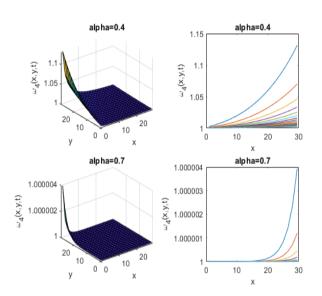


Figure 5. Kink wave of ω_4

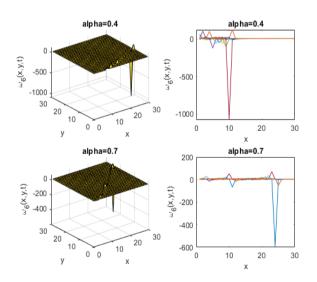
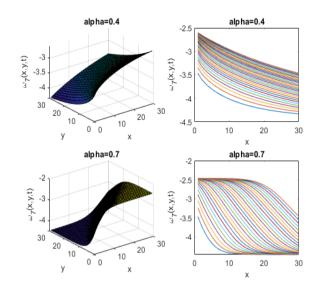
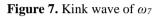
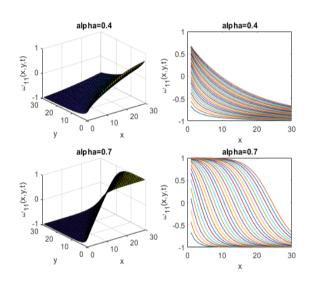
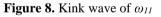


Figure 6. Periodic wave of ω_6









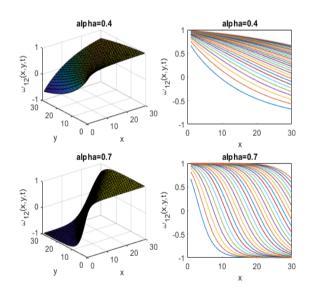


Figure 9. Kink wave of ω_{12}

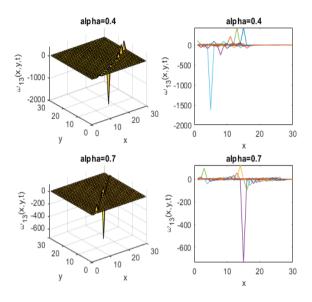


Figure 10. Periodic wave of ω_{13}

3.2 The non-linear space and time fractional of (2+1)dimensional GKP equation

Below are the exact results of traveling waves through the non-linear space and time fractional GKP equation:

$$D_x^{\alpha} \left(D_t^{\alpha} \omega + 6\omega D_x^{\alpha} \omega + 6\omega^2 D_x^{\alpha} \omega + D_x^{3\alpha} \omega \right) + D_y^{2\alpha} \omega = 0, \quad (51)$$

where, $t \ge 0$, $0 \le a \le 1$ and $\omega = \omega(x, y, t)$. Assuming that $\omega(x, y, t) = \Theta(\delta)$ and using transformation in Eq. (24) again:

$$r(-c\Theta' + 6r\Theta\Theta' + 6r\Theta^2\Theta' + r^3\Theta'')' + s^2\Theta'' = 0.$$
 (52)

when, Eq. (52) is integrated twice with a constant of zero, the result is:

$$-cr\Theta + 3r^2\Theta^2 + 2r^2\Theta^3 + r^4\frac{d^2\Theta}{d\delta^2} + s^2\Theta = 0.$$
 (53)

After bringing Eq. (53) into balance, we found that K=1. As a result, Eq. (10) evolved into:

$$\Theta(\delta) = b_0 + b_1 G(\delta). \tag{54}$$

Eq. (54) will be used in replacement of Eq. (53). In order to ensure that each coefficient was equivalent to zero, we first gathered up all of the words that belonged to the same power of $G(\delta)$ and then proceeded to do the following:

$$G^{0}(\delta): -b_{0}cr + 3b_{0}^{2}r^{2} + 2b_{0}^{3}r^{2} + b_{0}s^{2} = 0,$$
 (55)

$$G^{1}(\delta): -b_{1}cr + 6b_{0}b_{1}r^{2} + 6b_{0}^{2}b_{1}r^{2} + b_{1}r^{4}\eta^{2} + b_{1}s^{2} = 0, \qquad (56)$$

$$G^{2}(\delta): 3b_{1}^{2}r^{2} + 6b_{0}b_{1}^{2}r^{2} + 3b_{1}r^{4}\eta\xi = 0,$$
(57)

$$G^{3}(\delta): 2b_{1}^{3}r^{2} + 2b_{1}r^{4}\xi^{2} = 0.$$
(58)

We reach the following result after calculating out the solution to the system of Eqns. (55)-(58):

$$b_0 = \frac{-1\pm r\eta i}{2},\tag{59}$$

$$b_{\rm l} = \pm r \xi i, \tag{60}$$

$$c = \frac{s^2 - 2b_0^2 r^2 - r^4 \eta^2}{r}.$$
 (61)

Eqns. (12)-(14), (26), and (59)-(61) give for the description of the different exact 13 solutions of the non-linear space and time fractional cKG equations. This generates all answers distinct from that presented in Eq (8).

For η , $\eta^2 > 0$ and $\xi \neq 0$ these are real and not zero, then we get:

$$\omega_{\rm l} = \frac{-1 \pm r\eta i \pm ri\left(-\eta - \eta \tanh\left(\frac{\eta\delta}{2}\right)\right)}{2},\tag{62}$$

$$\omega_2 = \frac{-1 \pm r\eta i \pm ri\left(-\eta - \eta \coth\left(\frac{\eta\delta}{2}\right)\right)}{2},\tag{63}$$

$$\omega_3 = \frac{-1 \pm r\eta i \pm ri\left(-\eta - \eta \tanh\left(\eta\delta\right) \mp i\eta \operatorname{sech}\left(\eta\delta\right)\right)}{2}, \quad (64)$$

$$\omega_4 = \frac{-1 \pm r\eta i \pm ri\left(-\eta - \eta \coth\left(\eta\delta\right) \mp \eta \operatorname{csch}\left(\eta\delta\right)\right)}{2}, \quad (65)$$

$$\omega_{5} = \frac{-1 \pm r\eta i}{2} \pm \frac{ri}{4} \left(-2\eta - \eta \tanh\left(\frac{\eta\delta}{4}\right) - \eta \coth\left(\frac{\eta\delta}{4}\right) \right), \quad (66)$$

$$\omega_6 = \frac{-1 \pm r\eta i}{2} \pm ri \left(\frac{\eta \sqrt{Q^2 + R^2} - \eta Q \cosh(\eta \delta)}{2Q \sinh(\eta \delta) + 2R} - \frac{\eta}{2} \right), \quad (67)$$

$$\omega_7 = \frac{-1 \pm r\eta i}{2} \pm ri \left(\frac{-\eta \sqrt{R^2 - Q^2} - \eta Q \sinh(\eta \delta)}{2Q \cosh(\eta \delta) + 2R} - \frac{\eta}{2} \right), \quad (68)$$

where, Q and R are two non-zero real constant that satisfy $R^2 - Q^2 > 0$.

$$\omega_8 = \frac{-1 \pm r\eta i}{2} \pm \frac{ri\eta e^{\eta\delta}}{1 \mp e^{\eta\delta}},\tag{69}$$

$$\omega_9 = \frac{-1\pm r\eta i}{2} \pm \frac{ri\eta e^{\eta \delta}}{i\mp e^{\eta \delta}},\tag{70}$$

$$\omega_{10} = \frac{-1 \pm r\eta i}{2} \pm ri \left(\frac{\eta \sqrt{Q^2 - R^2} \pm \eta \left(Q e^{\eta \delta} - iR \right)}{\mp Q \left(e^{\eta \delta} - e^{-\eta \delta} \right) \pm 2iR} \right), \quad (71)$$

where, Q and R are two non-zero real constant that satisfy $Q^2 - R^2 > 0$.

$$\omega_{11} = \frac{-1 \pm r\eta i}{2} \mp \frac{ri\eta \phi e^{\eta \delta}}{1 + \phi e^{\eta \delta}},\tag{72}$$

$$\omega_{12} = \frac{-1 \pm r\eta i}{2} \mp \frac{ri\eta e^{\eta\delta}}{\phi + e^{\eta\delta}},\tag{73}$$

where, ϕ is an arbitrary constant.

For $\eta=0$ and $\xi\neq 0$ and arbitrary constant ψ , the solution to Eq. (10) is:

$$\omega_{13} = \frac{-1 \pm r\eta i}{2} \mp \frac{r\xi i}{\xi \delta + \psi},\tag{74}$$

where,
$$\delta = \frac{rx^{\alpha}}{\Gamma(\alpha+1)} + \frac{sy^{\alpha}}{\Gamma(\alpha+1)} \mp \frac{\left(s^2 - 2b_0^2r^2 - r^4\eta^2\right)t^{\alpha}}{r\Gamma(\alpha+1)}.$$

4. CONCLUSIONS

In this exploration, we were able to solve some non-linear fractional equations of crystal dislocation and internal waves on ocean shelf, known as the fractional cKG equation and the fractional GKP equation respectively. The exact solutions to the fractional cKG equation are offered in 13 different situations as Eqns. (38)-(50), which are more varied than the solutions obtained by the modified simple equation method [21]. Following the adjustment of a few parameters, some physical waves of these equations were found to be kink waves, solitary waves and periodic waves as seen in Figures 1-10. The exact solutions to the fractional GKP equation as seen in Eqns. (62)-(74) are complex solutions. There are 13 solutions total, which is one more than the number of solutions found using the (G'/G, 1/G)-Expansion method [26]. It can be shown that the generalized Bernoulli equation method is a highly successful way for solving non-linear fractional PDEs, and that this method will offer solutions to additional nonlinear fractional equations.

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