The effects of fin height, fin-tube contact thickness and louver length on the performance of a compact fin-and-tube heat exchanger

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ABSTRACT

In this paper, the effects of fin height, louver length and fin-tube contact thickness on the amount of heat transfer and pressure drop in a compact louvered fin-and-tube heat exchanger were studied experimentally and numerically using the e – NTU method. The effects of fin-tube contact thickness (with the variations of this thickness being more than or less than fin thickness variation) and fin height and also the relationship between Louvre length and fin height were examined. To validate the modeling, first, the numerical model was compared with an experimental prototype, and a good agreement was observed between the experimental and numerical results. The modeling results indicate that the increase in the fin-tube contact thickness, until the contact thickness becomes equal to fin thickness, leads to the improvement of heat exchanger performance; but beyond that, it is ineffective. Also, heat exchanger performance improves with the increase of louver length at a fixed fin height. According to the results, the minimum Louvre length should be 1.0 mm less than the fin height. An analytical equation relating Louvre length to fin height has been obtained, which agrees with model results by up to 98%.

1. INTRODUCTION

Tube heat exchangers and louvered fin are widely used in HVAC and refrigeration systems and are classified into evaporators and condensers. Many studies have been conducted in order to improve the efficiency of these heat exchangers and to save energy. In recent years, researchers have tried to develop high performance heat exchangers by changing the simple fin-and-tube heat exchangers with plain fins into advanced compact heat exchangers with louvered fins [1-6]. Louvered fins provide a number of interrupting surfaces which interact with boundary layers to form a complex flow pattern that increases the heat transfer rate. Therefore, investigating the effect of louvered fin geometry on fluid flow and heat transfer is extremely important for designing an efficient heat exchanger.

Marlow et al. [7] explored the inlet region of louvered fin heat exchangers. Their research indicated that the area of this inlet region depends on a particular geometry. They showed the existence of frequency components in the flow behind a fully-developed louver. By varying the geometrical parameters, Karthik et al. [8] performed experimental and parametric analyses in order to study the thermo hydraulic performance of a compact heat exchanger with louvered fins. They showed that the increase in both the transverse and longitudinal tube pitches can lead to a higher pressure drop at un-louvered fin surfaces. Cuevas et al. [9] used Kandlikar classification to investigate the thermo-hydraulic performance of a louvered fin and flat tube minichannel heat exchanger. Pega et al. [10] studied the effect of louver angle on the performance of a heat exchanger with serpentine fins and flat tubes in a refrigeration system. They found that, with the increase of louver angle, the pressure drop at the beginning of the first frosting cycle increases for all fin pitches. Jang and Chen [11] numerically studied the optimization of louver angle in a louvered-fin heat exchanger. To predict the time-varying performance of folded louvered fins in microchannel heat exchangers, a model was developed which successfully predicts the amount of heat transfer in these systems [12]. The transient and steady-state flow conditions in heat exchangers with double-row and triple-row multi-louvered fins were investigated in order to estimate the performance of these heat exchangers [13].

Vaisi et al. [14] studied the effect of geometry optimization on the performance of a compact louvered-fin heat exchanger. They investigated the air-side heat transfer and pressure drop characteristics of flow over louvered fins and found out that by increasing the number of louvered fins in each tube row, the amount of heat transfer rate increases. Also, they analyzed the effects of different geometrical parameters including louver angle, louver pitch, number of louver, non-louvered length of fin inlet and outlet, and redirection distance on the heat transfer and pressure drop characteristics of compact louvered fin-and-tube heat exchangers experimentally and numerically [15]. Dong et al. [16] obtained a correlation between heat transfer and pressure drop for different types of compact heat exchangers with multi-louvered fins. Their results showed that fin pitch and fin length have significant effects on heat transfer coefficient and pressure drop as a function of forward air velocity.

The effect of transverse tube pitch on the heat transfer performance of compact heat exchangers was numerically
investigated by Hu et al. [17]. Their results show that at the same forward inlet air velocity in a heat exchanger, the overall average Nusselt number and pressure drop are reduced by increasing the transverse tube pitch. Ryu et al. [18] presented heat transfer and fluid flow correlations that express the performance of heat exchangers with corrugated louvered fins. They numerically investigated the effects of friction factor $f$ and Colburn factor $j$ associated with corrugated louvered fins. The air-side fluid flow and heat transfer characteristics of a multi-row fin-and-tube heat exchanger with flat and louvered fins were analyzed by Carija et al. for a wide range of operating conditions [19]. They found out that louver length has the greatest influence on heat transfer capacity. The effects of the different parameters of a multi-louvered-fin heat exchanger with delta-winglet vortex generators on heat transfer and pressure drop under laminar flow conditions were analyzed by Dezan et al. [20]. The fluid flow and heat transfer characteristics of compact heat exchangers with single- and double-row flat tubes and louvered fins were numerically simulated by Malapure et al. [21]. They found that the local Nusselt number is substantially high at fin tips and at the leading and trailing edges of louvers. Numerical Study on Heat Transfer Enhancement in a Rectangular Duct with Incline Shaped Baffles were numerically studied by Parkpoom et al. [22]. They found that the optimum Re is 12600 and degree is 45.

A review of recent literature on the effects of geometrical parameters on the thermo-hydraulic performance of fin-and-tube heat exchangers indicate that no related numerical analysis has been performed on the simultaneous effects of different parameters such as louver length, fin height and fin-tube contact thickness. Therefore, in this work, a fin-and-tube heat exchanger prototype has been manufactured and tested experimentally. The experimental tests were conducted for a few cases, and the obtained heat transfer rates and pressure drop coefficients were evaluated. After comparing the experimental and the numerical simulation results for some cases, several models were investigated numerically to observe the effect of each geometrical parameter on heat exchanger performance. A computer program based on the $\varepsilon – NTU$ method was also prepared to calculate the outlet temperature and pressure drop in the air section, and the numerical results were compared with the results obtained by the $\varepsilon – NTU$ model.

2. MATHEMATICAL ANALYSIS

2.1 Physical model

Fig. 1 shows the schematic model of the test radiator and the top and front sectional views. The arrangement of fins and tube in the test core can be seen in this figure. Because of the periodic and symmetric configuration of the test core, only one fin pitch in the spanwise direction of air flow and one water tube pitch in the lateral direction have been considered as the computational domain.

![Figure 1. General view of finned tube compact heat exchanger](image)

2.2 Governing equations

The governing equations for a 3D steady-state flow include the following continuity, momentum and energy equations:

Mass conservation:

$$\frac{\partial}{\partial x_i}(\rho u_i) = 0$$  \hspace{1cm} (1)

Momentum equation:

$$\frac{\partial}{\partial x_i}(\rho u_i u_j) = \frac{\partial}{\partial x_i}\left(\mu \frac{\partial u_i}{\partial x_i} + \frac{\partial u_i}{\partial x_j}\right) - \frac{\partial p}{\partial x_j}$$  \hspace{1cm} (2)

Energy equation:

$$\frac{\partial}{\partial x_i}(\rho C_p u_i T) = \frac{\partial}{\partial x_i}(k \frac{\partial T}{\partial x_i})$$  \hspace{1cm} (3)

In the above equations, $u_i$, $T$, $P$, $\rho$, $C_p$, $k$ indicate the mean velocity, temperature, pressure, density, dynamic viscosity, specific heat and thermal conductivity, respectively. In order to obtain the flow streamlines, pressure drop and temperature fields, the equations of continuity, momentum and energy are solved using the CFD techniques. Laminar and incompressible flow and constant air properties are assumed in solving these equations.
2.3 Numerical simulation and boundary conditions

In this paper, a 3D problem of fluid flow over a louvered fin of a finned-tube heat exchanger has been studied. The geometrical parameters and the configuration of louvered fins are depicted in Fig. 2, in which x, y and z are the streamwise, normal and spanwise coordinates, respectively. The height, length and width of computational domain are 1.25 mm, 25 mm and 4.58 mm, respectively. As Fig. 2 illustrates, each fin element between water tubes includes an inlet louver and an outlet louver with opposite directions. The middle surfaces of two adjacent fins are chosen as the upper and lower boundaries of a louver element. For side boundaries, the mid-section of water tubes on both sides of a louver element are considered as the left and right boundaries of the computational domain in the spanwise direction. Periodic boundary conditions are applied at the top and bottom as well as the left and right sides of the computational domain. The computational domain is extended by a distance of 5Fp along the entrance upstream of the louver element and a distance of 15Fp downstream of the louver element in order to avoid inlet and outlet flow influences and to be able to use fully developed flow conditions at the outlet.

Because of using elliptic governing equations, the conditions of all the boundaries must be considered in the computational domain. No-slip boundary conditions with zero flow velocity and constant wall temperature T_w = 353 K are considered at louvered fin surfaces. A temperature of T_in = 293 K and a uniform flow velocity of u_in = 12 m/s along a distance of 5Fp upstream of a louver element are established as the inlet boundary conditions. For outlet boundary conditions, Neumann boundary conditions (defined as a streamwise gradient of zero) are considered for all the variables along a distance of 15Fp downstream of a louver element. Moreover, wall boundary conditions are assumed for the two sides of louver element, and periodic boundary conditions are applied at the upper and lower bounds of the computational domain.

![Figure 2. General view of louvered fin](image)

In simulating this problem, an unstructured mesh with conical quadrilateral cells has been used along with a numeric Open Foam solver. The discretization of momentum and energy equations is performed by employing the second-order ‘Upwind’ method, and the discretization of the pressure term in the momentum equation is carried out by using the Brustho technique. The energy equation has been discretized implicitly, and the coupling of velocity and pressure fields by means of the ‘Simple’ method has been used to correct the pressure field. In numerical simulations, the under relaxation coefficients are used to further stabilize the iterative method. The correct selection of these coefficients totally depends on the experience gained by solving various problems. The sub-relaxation coefficients for the equations of pressure, momentum and energy have been considered as 0.3, 0.5 and 0.85, respectively.

2.4. Definition of performance parameters

The dimensionless pressure coefficient and heat transfer rate for the air side are obtained from the following equations:

\[ C_f = \frac{\Delta p}{\frac{1}{2} \rho u_{in}^2 f_{hf}} \]  
\[ Q = \rho u_{in} A_c \Delta T_f (T_{a, out} - T_{a, in}) \]  

where \( \Delta p \), \( u_{in} \), \( A_c \), \( D_{hi} \), \( T_{a, in} \) and \( A_c \) are the air side pressure drop, inlet velocity, fin length, hydraulic diameter of flow cross section, inlet air temperature, outlet air temperature and the cross sectional area of flow on the air side, respectively. The heat transfer coefficient and the Nusselt number, Nu, by using the logarithmic mean temperature difference (LMTD) method, are determined as:

\[ h_c = \frac{q}{\Delta T_m} \]  
\[ N u = \frac{h_c F_p}{k} \]  

where \( \Delta T_m \) (LMTD) is defined as:

\[ \Delta T_m = \frac{(\Delta T_{out} - \Delta T_{in})}{\ln((\Delta T_{out} - T_{a, in})/(\Delta T_{out} - T_{a, out}))} \]

where \( \Delta T_{out} \) and \( \Delta T_{in} \) are the temperature drops between outlet and inlet temperatures, \( T_{a, out} \) and \( T_{a, in} \) are the temperatures at the outlet and inlet, respectively.
where:

\[ NTU = \frac{UA}{c_{\text{min}}} \]  
\[ \varepsilon = \frac{\dot{Q}}{q_{\text{max}}} \]  
\[ C_r = \frac{c_{\text{min}}}{c_{\text{max}}} \]

The heat exchanger efficiency is used for perpendicular flow with two non-mixed fluids using the following equation [22]:

\[ \varepsilon = 1 - \exp\left(\frac{1}{C_r}\right) \cdot (NTU)^{0.22} \cdot \exp[-C_r(NTU)^{0.78}] - 1 \]

### 3. EXPERIMENTAL SETUP

![Figure 3. A view of experimental setup](image)

Fig. 3 shows the apparatus of the experimental equipment used in this investigation. The examined heat exchanger is placed in a test rig comprising an open air channel (including a test section, a laminar flow element, and a motor-controlled ventilator) and a closed water cycle. The galvanized steel air channel has a cross section of 800 x 800 mm². In the open-loop wind tunnel, air is circulated by a variable-speed centrifugal fan which is driven by a frequency-controlled motor. Using this mechanism, different mass flow rates of air can be produced. At the air channel inlet, a liquid-to-air heat exchanger is used to cool the air temperature. In the closed-loop water cycle, cold water is circulated by a rotary gear pump, and the water temperature is controlled via a thermal conditioning system. The cooling air enters the test section and flows through the louvered fin-and-tube heat exchanger (The geometric specifications of the heat exchanger are listed in Table 1). The heat exchanger itself is placed in a separate frame within the test section. In order to reduce heat losses that may affect temperature measurements, this frame and subsequent measuring units are completely insulated by foam panels. Measurements are taken at both the inlet and outlet of the heat exchanger. The test section is also carefully insulated to eliminate heat losses between measuring stations. The temperatures of heat exchangers at the inlet and outlet are measured by means of 12 K-type thermocouples. Once the tunnel reaches steady state, an average of 180 temperature measurements are taken at each thermocouple location. The pressure drop across the test section is measured by using two pressure transducers calibrated to an accuracy of ± 0.09%. One of these transducers is placed at heat exchanger inlet and the other is positioned after the laminar flow element. To obtain the pressure drops across the louvered array and the laminar flow element, 1100 and 6500 sample measurements are taken and averaged, respectively. For every air velocity, roughly, 350 measurements are averaged to obtain the air-side pressure drop. A mass flow meter (± 0.5%) is used to obtain the flow rate of air at the heat exchanger outlet. A laminar flow element with a 2:1 nozzle area reduction is placed after the test section to provide a uniform flow. The flow rates through the test section are measured by means of a laminar flow element. A single-phase mixture of ethylene glycol and water is used for flow measurements in the water-side of heat exchanger. This cycle consists of K-type thermocouples, an electronic flow meter, a circulation pump, thermal conditioning, manometer and a differential pressure transducer. A water boiler and a gear pump supply the hot fluid for the heat exchanger in the test section; and a thermal conditioner controls the temperature of the hot water. The water temperatures at the inlet and outlet are measured by K-type thermocouples, which are read by a scanner and a high precision voltmeter. The pressure drops in the water-side are measured by a differential pressure transducer and checked by a manometer.

### Table 1. Geometrical parameters of the louvered fin-and-tube heat exchanger

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Tube material</th>
<th>Fin material</th>
<th>Air flow re-direction length (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tube material</td>
<td>Aluminum</td>
<td>Aluminum</td>
<td>2.5</td>
</tr>
<tr>
<td>Tube surface area (mm²)</td>
<td>2.1 × 22.93</td>
<td>0.07</td>
<td></td>
</tr>
<tr>
<td>Tube thickness (mm)</td>
<td>0.28</td>
<td>9.17</td>
<td></td>
</tr>
<tr>
<td>Core width (mm)</td>
<td>383</td>
<td>25</td>
<td></td>
</tr>
<tr>
<td>Number of tube rows in the airflow</td>
<td>1</td>
<td>7.4</td>
<td></td>
</tr>
<tr>
<td>Louver pitch (mm)</td>
<td>1</td>
<td>24</td>
<td></td>
</tr>
<tr>
<td>Louvers per tube row</td>
<td>18</td>
<td>18</td>
<td></td>
</tr>
<tr>
<td>Louver angle (degree)</td>
<td>24</td>
<td>320</td>
<td></td>
</tr>
<tr>
<td>Header to header length (mm)</td>
<td>800</td>
<td>2.5</td>
<td></td>
</tr>
</tbody>
</table>
4. RESULTS AND DISCUSSION

In this section, the effects of different geometrical parameters on the thermal performance of a heat exchanger have been studied.

4.1 Validation

In addition to simulating fluid flows and evaluating the heat transfer and pressure drop features of heat exchangers using the CFD method, the obtained results are compared with experimental data for several cases in order to validate the numerical simulations. For this purpose, an aluminum louvered fin-and-tube heat exchanger prototype is manufactured and tested in a wind tunnel. For all the performed simulations, the mass flow rate of water is \( m = 40 \text{lit/min} \), inlet water temperature is \( T = 80 \text{°C} \) and the inlet air temperature is \( T = 20 \text{°C} \). In order to validate the numerical results, an experimental model was fabricated and tested. Unstructured meshing with conical quadrilateral cells has been used in the numerical simulations performed in the present work. For mesh independency, several grids with different numbers of meshes were employed. The outlet temperature and pressure coefficient were examined for grids which the independence of solution from quantity of mesh was selected.

The experimental model was placed in a wind tunnel and its performance was evaluated under different boundary conditions. The results of several tests on the prototype, under different conditions, were compared with the simulation results. After validating the numerical results, several models were numerically simulated and studied for different geometries and boundary conditions. As Table 2 and Fig. 4 indicate, the experimental and numerical results are in good agreement. Assuming the same temperature for the meshed surfaces of heat exchanger in the numerical models of all tubes and fins, from top to bottom and assuming a perpendicular direction to flow, a 3D element at the beginning and one at the end of the tube are analyzed.

![Figure 4. Comparison of the experimental and numerical temperature profile of the fluid in different inlet velocities](image)

According to these results, the average outlet flow (air) temperature decreases almost linearly by increasing the inlet velocity. The results also indicate that at lower air velocities, the error between experimental and numerical results is rather large, and that it diminishes at higher air velocities. Because of the good match between the results in Tables 3 and 4, several models with different geometries and boundary conditions were simulated numerically to demonstrate the effects of different geometrical parameters on the performance of louvered fin heat exchangers. The maximum and minimum percentage errors between experimental and numerical results are 3.51% and 0.13% for temperature, 8.75% and 4.54% for friction coefficient, respectively.

<table>
<thead>
<tr>
<th>Inlet air velocity (m/s)</th>
<th>Exp. Outlet air temperature (°C)</th>
<th>Num. Outlet air temperature (°C)</th>
<th>Error (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>6.04</td>
<td>49.86</td>
<td>51.61</td>
<td>3.51</td>
</tr>
<tr>
<td>8.05</td>
<td>46.13</td>
<td>47.42</td>
<td>2.80</td>
</tr>
<tr>
<td>10.06</td>
<td>43.59</td>
<td>44.06</td>
<td>1.08</td>
</tr>
<tr>
<td>12.02</td>
<td>41.53</td>
<td>41.44</td>
<td>0.22</td>
</tr>
<tr>
<td>14.03</td>
<td>39.47</td>
<td>39.42</td>
<td>0.13</td>
</tr>
<tr>
<td>16.04</td>
<td>37.92</td>
<td>37.68</td>
<td>0.62</td>
</tr>
</tbody>
</table>

4.2 The effect of fin-tube contact thickness

In order to illustrate different parameters such as the Nusselt number and pressure drop coefficients in the same figure, these parameters are non-dimensionalized with respect to their maximum value, as \( f/ f_{\text{max}} \), and the results are presented in a range of [0-1]. Fig. 5 shows the effect of fin-tube contact thickness on pressure drop coefficient and Nusselt number. As this figure indicates, by increasing the fin-tube contact thickness as high as the fin thickness (7 microns), the amount of heat transfer increases and then decreases; but the coefficient of friction at first increases to the contact thickness and then remains constant. The increase of fin-tube contact thickness enhances the rate of heat transfer between fin surfaces as fluid passes through the fins. Due to the fact that in the range of the contact thickness to the tube, which is more than the thickness of the fin, the heat is transferred from the tube to the fluid and in which the flow range does not pass through the blade, there is no time of heat transfer to other points. Also, by increasing the thickness, the surface of contact between fin and fluid is reduced, especially at the fin-tube contact zone, and pressure drop is increased. At fin-tube contact thicknesses greater than fin thickness (7 microns), there is no significant change in the amount of pressure drop.

![Figure 5. The non-dimensional variation of Nusselt number and pressure drop coefficient at different thickness of the fin contact surface](image)
Fig. 6 shows the changes of fluid temperature at the start of louvered fins, as the fin-tube contact surface increases. As it is observed in this figure, by increasing the fin-tube contact thickness, fin surface increases, thereby increasing the amount of heat conduction and heat transfer between fin and fluid. Due to the constant inlet temperature, fluid temperature rises where the louvered fins begin.

4.3 The effect of louver length

Figs. 7 and 8 show the variations of louver length with fin height. With the increase of louver length, the suction and blowing cross sections in fins increase. Thus, a larger volume of fluid passes through the fins and thereby, the rate of heat exchange between fins and fluid increases. Consequently, the amount of heat transfer and pressure drop increases. However, for mechanical strength reasons, louver length should be at least 1.0 mm less than fin height. According to the results, at louver lengths of 7.8, 6.6 and 5.7 mm and fin heights of 9.17, 8 and 7 mm, respectively, the amount of heat transfer increases first and then diminishes or remains almost unchanged.

Fig. 7. The non-dimensional variation of pressure drop coefficient at different louver length for difference fin height

Fig. 8. The non-dimensional variation of Nusselt number at different louver length for difference fin height

Fig. 9 shows the temperature distribution obtained by changing the louver length and keeping the fin height constant at 8 mm. With the increase of louver length, heat transfer and outlet fluid temperature increase first and then remain almost constant. Because suction and blowing flow rates go up with the increase of louver length, the volume of fluid passing through the ducts increases, and more energy is transferred. However, with the increased duct length, the side area of tubes becomes too small. This not only diminishes the mechanical strength, but it also reduces the volume of fluid required for heat transfer with the fins; and so there is less energy transfer.

Fig. 10 shows the pressure distribution caused by varying the louver length and keeping the fin height constant at 8 mm. Pressure drop increases with the increase of louver length; because of increasing the cross sections of suction and blowing flows. Because the volume of fluid passing through the cross sections and the contact surface increases, which increases the coefficient of friction and pressure drop. Also, the volume of fluid passing through the channels is greater than the change of contact thickness; and this increases the coefficient of friction and pressure drop. Also, the volume of fluid passing through these cross sections and the contact surface increase, which increase the coefficient of friction and pressure drop.

Fig. 14 shows the variation of temperature profile in the x-direction. It can be seen the fluid temperature increases with along x-direction.
4.4 The effect of inlet Reynolds number

By changing the inlet Reynolds number, the variations of temperature and pressure contours on fin have been investigated. As the Reynolds number increases, the rate of flow passing over the fins becomes greater. Also, the increase of Reynolds number leads to the increase of convection heat transfer between fin surface and fluid flow. Also, with regards to the amount of heat transfer according to Eq. 5 and the constant inlet fluid temperature, the outlet fluid temperature is reduced according to Fig. 12. In view of Eq. 4, due to the increase of flow velocity, the pressure fluctuations on fin increase with the increase of Reynolds number, according to Fig. 13.

4.5 The effect of fin height (length of inlet stream)

Fig. 14 shows the variations of outlet fluid temperature versus the ratio of louver length to fin height. By increasing the ratio of louver length to fin height, the rate of heat transfer between fin surface and fluid is increased, thereby raising the outlet fluid temperature. Also, at a constant ratio of louver length to fin height, the outlet fluid temperature decreases with the increase of fin height; this reduces the heat transfer and outlet fluid temperature, because the fluid passing over the fins does not have enough time for the exchange and transfer of heat with the fins.

Figure 15 shows the changes of dimensionless pressure drop versus the ratio of louver length to fin height. With the increase in the ratio of louver length to fin height, pressure drop increases, because the volume of the fluid passes through increasing the cross-section with the blowing and the suction, the surface of the contact with the Louvre fin increases. In addition, at a constant ratio of louver length to fin height, pressure drop diminishes with the increase of fin height.
Figure 14. The variation of outlet fluid temperature at different with the ratio of Louvre length to the fin height

Figure 15. The non-dimensional variation of presser coefficient at different with the ratio of Louvre length to the fin height

Figure 16. The variation of optimization louver length at different fin height

Using the MATLAB code and the correlations between experimental and numerical data, some formulas were derived that relate fin height to louver length. After applying a genetic algorithm to minimize error (least square method), Eq. 17 was obtained for this purpose.

\[ F_{h} = 0.66666 + 1.11111 L_{L} + 0.00000001 \times 27 L_{L}^{2} \]  

In this equation, \( L_{L} \) is the louver length and \( F_{h} \) is the fin height.

This numerical modeling can be optimized for any louver length. The presented equation showed up to 98% agreement with the experimental and numerical models. In Table 3, louver lengths at different fin heights obtained experimentally and analytically have been compared. The fin heights obtained in terms of optimal louver length closely match the actual fin heights used in the industry.

Table 3. The variation of fin height with different louver length

<table>
<thead>
<tr>
<th>Louver length (mm)</th>
<th>Real fin height (mm)</th>
<th>Calculate fin height (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>4</td>
<td>3.99</td>
</tr>
<tr>
<td>3.9</td>
<td>5</td>
<td>4.99</td>
</tr>
<tr>
<td>4.8</td>
<td>6</td>
<td>6.00</td>
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<tr>
<td>5.7</td>
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<td>7.00</td>
</tr>
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<td>8</td>
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<tr>
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<td>9.3</td>
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<td>11.00</td>
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<td>11.1</td>
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<td>12.99</td>
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<tr>
<td>12</td>
<td>14</td>
<td>13.99</td>
</tr>
</tbody>
</table>

5. CONCLUSION

In this work, the effects of fin height, optimal louver length and fin-louver contact thickness on the amount of heat transfer and pressure drop in a compact heat exchanger were investigated. The variable parameters included the fin-tube contact thickness, louver length and fin height. For validation, several experimental tests were conducted in a wind tunnel facility, and a good agreement was observed between the experimental and numerical results.

The conclusions of this research can be summarized as follows:

1. The amounts of heat transfer and pressure drop increase by increasing the fin-tube contact thickness up to the fin thickness; a further increase in the fin-tube contact thickness has no effect on heat exchanger performance.
2. By increasing the ratio of louver length to fin height, the amounts of heat transfer and pressure drop are increased.
3. At a constant ratio of louver length to fin height, the amounts of heat transfer and pressure drop diminish with the increase of fin height.
4. For the sake of mechanical strength, louver length should be at least 1.0 mm less than fin height. Considering both the experimental and numerical results, a formula relating louver length to fin height has been derived that agrees up to 98% with the modeling results.
5. The optimal louver lengths of 5.7, 6.6 and 7.6 mm are obtained for fin heights of 7, 8 and 9.17 mm, respectively.
6. The ratio of optimal louver length to fin height is...
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REFERENCES


NOMENCLATURE

\( A \) Total surface area \([m^2]\)
\( A_c \) Cross section air flow \([m^2]\)
\( C \) Heat capacity rate \([J/kg \, K]\)
\( C_p \) Specific heat \([J/kg \, K]\)
\( C_r \) Capacity rate ratio [-]
\( D_{hf} \) Hydraulic diameter \([mm]\)
\( F_h \) Fin height \([mm]\)
\( F_p \) Fin pitch \([mm]\)
\( h_c \) Heat transfer coefficient \([W/m^2 \, K]\)
\( H_f \) Radiator height \([mm]\)
\( k \) Thermal conductivity \([W/m \, K]\)

**Logarithmic mean temperature difference**

\( LMTD \) \([K]\)
\( l_f \) Fin length \([mm]\)
\( L_f \) Radiator width \([mm]\)
\( L_L \) Louver height \([mm]\)
\( L_P \) Louver pitch \([mm]\)
\( L_R \) Distance of inlet and re-direction region \([mm]\)
\( N_L \) Louver number [-]
\( N_u \) Nusselt number [-]
\( NTU \) Number of transfer unit [-]
\( p \) Pressure \([Pa]\)
\( \Delta p \) Pressure drop \([Pa]\)

\( UA \) Overall thermal conductivity \([W/ \, K]\)
\( \dot{Q} \) Heat transfer rate \([W]\)
\( S_1 \) Non-louvered inlet and exit fin length \([mm]\)
\( S_2 \) Re-direction length \([mm]\)
\( t \) Fin thickness \([mm]\)
\( T \) Temperature \([K]\)
\( t_f \) Fin depth in flow direction \([mm]\)
\( u \) Velocity \([m/s]\)

**Greek symbols**

\( \varepsilon \) Effectiveness
\( \theta_L \) Louver angle \([^\circ]\)
\( \mu \) Dynamic viscosity \([Ns/m^2]\)
\( \rho \) Density \([kg/m^3]\)

**Subscripts**

\( a \) Air
\( c \) Cold
\( f \) Fin
\( h \) Hot
\( in \) Inlet
\( max \) Maximum
\( min \) Minimum
\( out \) Outlet